

Apr 26, 97 12:48

binomialFilter.m

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```

% KERNEL = binomialFilter(size)
%
% Returns a vector of binomial coefficients of order (size-1) .
%
% Ero Simoncelli, 2/97.
function [kernel] = binomialFilter(sz)
if (sz < 2)
    error('size argument must be larger than 1');
end
kernel = [0.5 0.5]';
for n=1:sz-2
    kernel = conv([0.5 0.5]', kernel);
end

```

Aug 06, 03 18:04

blurDn.m

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```

% RES = blurDn(IM, LEVELS, FILT)
%
% Blur and downsample an image. The blurring is done with filter
% kernel specified by FILT (default = 'binom5'), which can be a string
% (to be passed to namedFilter), a vector (applied separably as a 1D
% convolution kernel in X and Y), or a matrix (applied as a 2D
% convolution kernel). The downsampling is always by 2 in each
% direction.
%
% The procedure is applied recursively LEVELS times (default=1).
%
% Ero Simoncelli, 3/97.
function res = blurDn(im, nlevs, filt)
%-----
%% OPTIONAL ARGS:
if (exist('nlevs') ~= 1)
    nlevs = 1;
end
if (exist('filt') ~= 1)
    filt = 'binom5';
end
%-----
if isstr(filt)
    filt = namedFilter(filt);
end
filt = filt/sum(filt(:));
if nlevs > 1
    im = blurDn(im,nlevs-1,filt);
end
if (nlevs >= 1)
    if (any(size(im)==1))
        if (~any(size(filt)==1))
            error('Cant apply 2D filter to 1D signal');
        end
        if (size(im,2)==1)
            filt = filt(:);
        else
            filt = filt(:)';
        end
        res = corrDn(im,filt,'reflect1',(size(im)~=1)+1);
    elseif (any(size(filt)==1))
        filt = filt(:);
        res = corrDn(im,filt,'reflect1',[2 1]);
        res = corrDn(res,filt','reflect1',[1 2]);
    else
        res = corrDn(im,filt,'reflect1',[2 2]);
    end
end
res = im;
end

```

Apr 16, 98 17:43

buildGpyr.m

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```

% [PYR, INDICES] = buildGpyr(IM, HEIGHT, FILT, EDGES)
%
% Construct a Gaussian pyramid on matrix IM.
%
% HEIGHT (optional) specifies the number of pyramid levels to build. Default
% is 1+maxPyrHt(size(IM),size(FILT)).
% You can also specify 'auto' to use this value.
%
% FILT (optional) can be a string naming a standard filter (see
% namedFilter), or a vector which will be used for (separable)
% convolution. Default = 'binom5'. EDGES specifies edge-handling, and
% defaults to 'reflect1' (see corrDn).
%
% PYR is a vector containing the N pyramid subbands, ordered from fine
% to coarse. INDICES is an Nx2 matrix containing the sizes of
% each subband. This is compatible with the MatLab Wavelet toolbox.
%
% Eero Simoncelli, 6/96.

function [pyr,pind] = buildGpyr(im, ht, filt, edges)

if (nargin < 1)
    error('First argument (IM) is required');
end

im_sz = size(im);

%-----
%% OPTIONAL ARGS:

if (exist('filt') ~= 1)
    filt = 'binom5';
end

if isstr(filt)
    filt = namedFilter(filt);
end

if ( (size(filt,1) > 1) & (size(filt,2) > 1) )
    error('FILT should be a 1D filter (i.e., a vector)');
else
    filt = filt(:);
end

max_ht = 1 + maxPyrHt(im_sz, size(filt,1));
if ( (exist('ht') ~= 1) | (ht == 'auto') )
    ht = max_ht;
else
    if (ht > max_ht)
        error(sprintf('Cannot build pyramid higher than %d levels.',max_ht));
    end
end

if (exist('edges') ~= 1)
    edges = 'reflect1';
end

%-----

if (ht <= 1)

    pyr = im(:);
    pind = im_sz;

else

    if (im_sz(2) == 1)
        lo2 = corrDn(im, filt, edges, [2 1], [1 1]);
    elseif (im_sz(1) == 1)
        lo2 = corrDn(im, filt, edges, [1 2], [1 1]);
    else
        lo = corrDn(im, filt, edges, [1 2], [1 1]);
        lo2 = corrDn(lo, filt, edges, [2 1], [1 1]);
    end

    [npyr,nind] = buildGpyr(lo2, ht-1, filt, edges);

    pyr = [im(:); npyr];
    pind = [im_sz; nind];

end

```

Apr 16, 98 17:42

buildLpyr.m

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```

% [PYR, INDICES] = buildLpyr(IM, HEIGHT, FILT1, FILT2, EDGES)
%
% Construct a Laplacian pyramid on matrix (or vector) IM.
%
% HEIGHT (optional) specifies the number of pyramid levels to build. Default
% is 1+maxPyrHt(size(IM),size(FILT)). You can also specify 'auto' to
% use this value.
%
% FILT1 (optional) can be a string naming a standard filter (see
% namedFilter), or a vector which will be used for (separable)
% convolution. Default = 'binom5'. FILT2 specifies the "expansion"
% filter (default = filt1). EDGES specifies edge-handling, and
% defaults to 'reflect1' (see corrDn).
%
% PYR is a vector containing the N pyramid subbands, ordered from fine
% to coarse. INDICES is an Nx2 matrix containing the sizes of
% each subband. This is compatible with the MatLab Wavelet toolbox.
%
% Eero Simoncelli, 6/96.

function [pyr,pind] = buildLpyr(im, ht, filt1, filt2, edges)

if (nargin < 1)
    error('First argument (IM) is required');
end

im_sz = size(im);

%-----
%% OPTIONAL ARGS:

if (exist('filt1') ~= 1)
    filt1 = 'binom5';
end

if isstr(filt1)
    filt1 = namedFilter(filt1);
end

if ( (size(filt1,1) > 1) & (size(filt1,2) > 1) )
    error('FILT1 should be a 1D filter (i.e., a vector)');
else
    filt1 = filt1(:);
end

if (exist('filt2') ~= 1)
    filt2 = filt1;
end

if isstr(filt2)
    filt2 = namedFilter(filt2);
end

if ( (size(filt2,1) > 1) & (size(filt2,2) > 1) )
    error('FILT2 should be a 1D filter (i.e., a vector)');
else
    filt2 = filt2(:);
end

max_ht = 1 + maxPyrHt(im_sz, max(size(filt1,1), size(filt2,1)));
if ( (exist('ht') ~= 1) | (ht == 'auto') )
    ht = max_ht;
else
    if (ht > max_ht)
        error(sprintf('Cannot build pyramid higher than %d levels.',max_ht));
    end
end

if (exist('edges') ~= 1)
    edges = 'reflect1';
end

%-----

if (ht <= 1)

    pyr = im(:);
    pind = im_sz;

else

    if (im_sz(2) == 1)
        lo2 = corrDn(im, filt1, edges, [2 1], [1 1]);
    elseif (im_sz(1) == 1)
        lo2 = corrDn(im, filt1, edges, [1 2], [1 1]);
    else
        lo = corrDn(im, filt1, edges, [1 2], [1 1]);
        int_sz = size(lo);
        lo2 = corrDn(lo, filt1, edges, [2 1], [1 1]);
    end

    [npyr,nind] = buildLpyr(lo2, ht-1, filt1, filt2, edges);

    if (im_sz(1) == 1)
        hi2 = upConv(lo2, filt2, edges, [1 2], [1 1], im_sz);
    elseif (im_sz(2) == 1)
        hi2 = upConv(lo2, filt2, edges, [2 1], [1 1], im_sz);
    else
        hi = upConv(lo2, filt2, edges, [2 1], [1 1], int_sz);
        hi2 = upConv(hi, filt2, edges, [1 2], [1 1], im_sz);
    end

    hi2 = im - hi2;

    pyr = [hi2(:); npyr];
    pind = [im_sz; nind];

end

```

Aug 28, 02 21:57

buildSFpyrLevs.m

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```

% [PYR, INDICES] = buildSFpyrLevs(LODFT, LOGRAD, XRCOS, YRCOS, ANGLE, HEIGHT, NB
ANDS)
%
% Recursive function for constructing levels of a steerable pyramid. This
% is called by buildSFpyr, and is not usually called directly.
%
% Eero Simoncelli, 5/97.
function [pyr,pind] = buildSFpyrLevs(lodft,log_rad,Xrcos,Yrcos,angle,ht,nbands);
if (ht <= 0)
    lo0 = ifft2(iftftshift(lodft));
    pyr = real(lo0(:));
    pind = size(lo0);
else
    bands = zeros(prod(size(lodft)), nbands);
    bind = zeros(nbands,2);
%
% log_rad = log_rad + 1;
Xrcos = Xrcos - log2(2); % shift origin of lut by 1 octave.
%
% lutsizes = 1024;
Xcosn = pi*[-(2*lutsizes+1):(lutsizes+1)]/lutsizes; % [-2*pi:pi]
order = nbands-1;
%% divide by sqrt(sum_n=0^(N-1) cos(pi*n/N)^(2(N-1)))
%% Thanks to Patrick Teo for writing this out :)
const = (2^(2*order))*(factorial(order)^2)/(nbands*factorial(2*order));
Ycosn = sqrt(const) * (cos(Xcosn)).^order;
himask = pointOp(log_rad, Yrcos, Xrcos(1), Xrcos(2)-Xrcos(1), 0);
for b = 1:nbands
    anglemask = pointOp(angle, Ycosn, Xcosn(1)+pi*(b-1)/nbands, Xcosn(2)-Xcosn(1)
);
    banddft = ((-sqrt(-1))^(nbands-1)) .* lodft .* anglemask .* himask;
    band = ifft2(iftftshift(banddft));
    bands(:,b) = real(band(:));
    bind(b,:) = size(band);
end
%
% dims = size(lodft);
ctr = ceil((dims+0.5)/2);
lodims = ceil((dims-0.5)/2);
loctr = ceil((lodims+0.5)/2);
lostart = ctr-loctr+1;
loend = lostart+lodims-1;
%
% log_rad = log_rad(lostart(1):loend(1),lostart(2):loend(2));
% angle = angle(lostart(1):loend(1),lostart(2):loend(2));
% lodft = lodft(lostart(1):loend(1),lostart(2):loend(2));
% YIrcos = abs(sqrt(1.0 - Yrcos.^2));
% lomask = pointOp(log_rad, YIrcos, Xrcos(1), Xrcos(2)-Xrcos(1), 0);
%
% lodft = lomask .* lodft;
%
% [npyr,nind] = buildSFpyrLevs(lodft, log_rad, Xrcos, Yrcos, angle, ht-1, nbands
);
%
% pyr = [bands(:); npyr];
% pind = [bind; nind];
end

```

Aug 14, 03 15:49

buildSFpyr.m

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```

% [PYR, INDICES, STEERMATRIX, HARMONICS] = buildSFpyr(IM, HEIGHT, ORDER, TWIDTH)
%
% Construct a steerable pyramid on matrix IM, in the Fourier domain.
% This is similar to buildSFpyr, except that:
%
% + Reconstruction is exact (within floating point errors)
% + It can produce any number of orientation bands.
% - Typically slower, especially for non-power-of-two sizes.
% - Boundary-handling is circular.
%
% HEIGHT (optional) specifies the number of pyramid levels to build. Default
% is maxPyrHt(size(IM),size(FILT));
%
% The squared radial functions tile the Fourier plane, with a raised-cosine
% falloff. Angular functions are cos(theta-k*pi/(K+1))^K, where K is
% the ORDER (one less than the number of orientation bands, default= 3).
%
% TWIDTH is the width of the transition region of the radial lowpass
% function, in octaves (default = 1, which gives a raised cosine for
% the bandpass filters).
%
% PYR is a vector containing the N pyramid subbands, ordered from fine
% to coarse. INDICES is an Nx2 matrix containing the sizes of
% each subband. This is compatible with the MatLab Wavelet toolbox.
% See the function STEER for a description of STEERMATRIX and HARMONICS.
%
% Eero Simoncelli, 5/97.
% See http://www.cis.upenn.edu/~eero/steerpyr.html for more
% information about the Steerable Pyramid image decomposition.
function [pyr,pind,steermtx,harmonics] = buildSFpyr(im, ht, order, twidth)
%-----
%% DEFAULTS:
max_ht = floor(log2(min(size(im)))) - 2;
if (exist('ht') ~= 1)
    ht = max_ht;
else
    if (ht > max_ht)
        error(sprintf('Cannot build pyramid higher than %d levels.',max_ht));
    end
end
if (exist('order') ~= 1)
    order = 3;
elseif ((order > 15) | (order < 0))
    fprintf(1,'Warning: ORDER must be an integer in the range [0,15]. Truncating.\n');
    order = min(max(order,0),15);
else
    order = round(order);
end
nbands = order+1;
if (exist('twidth') ~= 1)
    twidth = 1;
elseif (twidth <= 0)
    fprintf(1,'Warning: TWIDTH must be positive. Setting to 1.\n');
    twidth = 1;
end
%-----
%% Steering stuff:
if (mod((nbands),2) == 0)
    harmonics = [0:(nbands/2)-1]*2 + 1;
else
    harmonics = [0:(nbands-1)/2]*2;
end
steermtx = steer2HarmMtx(harmonics, pi*[0:nbands-1]/nbands, 'even');
%-----
%
% dims = size(im);
% ctr = ceil((dims+0.5)/2);
%
% [xramp,yramp] = meshgrid( ([1:dims(2)]-ctr(2))./(dims(2)/2), ...
% ([1:dims(1)]-ctr(1))./(dims(1)/2) );
% angle = atan2(yramp,xramp);
% log_rad = sqrt(xramp.^2 + yramp.^2);
% log_rad(ctr(1),ctr(2)) = log_rad(ctr(1),ctr(2)-1);
% log_rad = log2(log_rad);
%
% %% Radial transition function (a raised cosine in log-frequency):
% [Xrcos,Yrcos] = rcosFn(twidth,(-twidth/2),[0 1]);
% Yrcos = sqrt(Yrcos);
%
% YIrcos = sqrt(1.0 - Yrcos.^2);
% lo0mask = pointOp(log_rad, YIrcos, Xrcos(1), Xrcos(2)-Xrcos(1), 0);
% imdft = fftshift(fft2(im));
% lo0dft = imdft .* lo0mask;
%
% [pyr,pind] = buildSFpyrLevs(lo0dft, log_rad, Xrcos, Yrcos, angle, ht, nbands);
%
% hi0mask = pointOp(log_rad, Yrcos, Xrcos(1), Xrcos(2)-Xrcos(1), 0);
% hi0dft = imdft .* hi0mask;
% hi0 = ifft2(iftftshift(hi0dft));
%
% pyr = [real(hi0(:)); pyr];
% pind = [size(hi0); pind];

```

May 01, 97 18:56 **buildSpyrLevs.m** Page 1/1

```

% [PYR, INDICES] = buildSpyrLevs(LOIM, HEIGHT, LOFILT, BFILTS, EDGES)
%
% Recursive function for constructing levels of a steerable pyramid. This
% is called by buildSpyr, and is not usually called directly.
%
% Eroo Simoncelli, 6/96.
function [pyr,pind] = buildSpyrLevs(lo0,ht,lofilt,bfils,edges);
if (ht <= 0)
    pyr = lo0(:);
    pind = size(lo0);
else
    % Assume square filters:
    bfiltz = round(sqrt(size(bfils,1)));
    bands = zeros(prod(size(lo0)),size(bfils,2));
    bind = zeros(size(bfils,2),2);
    for b = 1:size(bfils,2)
        filt = reshape(bfils(:,b),bfiltz,bfiltz);
        band = corrDn(lo0, filt, edges);
        bands(:,b) = band(:);
        bind(b,:) = size(band);
    end
    lo = corrDn(lo0, lofilt, edges, [2 2], [1 1]);
    [npyr,nind] = buildSpyrLevs(lo, ht-1, lofilt, bfils, edges);
    pyr = [bands(:); npyr];
    pind = [bind; nind];
end

```

Apr 16, 98 17:44 **buildSpyr.m** Page 1/1

```

% [PYR, INDICES, STEERMTX, HARMONICS] = buildSpyr(IM, HEIGHT, FILTFILE, EDGES)
%
% Construct a steerable pyramid on matrix IM.
%
% HEIGHT (optional) specifies the number of pyramid levels to build. Default
% is maxPyrHt(size(IM),size(FILT)).
% You can also specify 'auto' to use this value.
%
% FILTFILE (optional) should be a string referring to an m-file that
% returns the rfilters. (examples: 'sp0Filters', 'sp1Filters',
% 'sp3Filters', 'sp5Filters'. default = 'sp1Filters'). EDGES specifies
% edge-handling, and defaults to 'reflect1' (see corrDn).
%
% PYR is a vector containing the N pyramid subbands, ordered from fine
% to coarse. INDICES is an Nx2 matrix containing the sizes of
% each subband. This is compatible with the MatLab Wavelet toolbox.
% See the function STEER for a description of STEERMTX and HARMONICS.
%
% Eroo Simoncelli, 6/96.
% See http://www.cis.upenn.edu/~eero/steerpyr.html for more
% information about the Steerable Pyramid image decomposition.
function [pyr,pind,steermtx,harmonics] = buildSpyr(im, ht, filtfile, edges)
%-----
%% DEFAULTS:
if (exist('filtfile') ~= 1)
    filtfile = 'sp1Filters';
end
if (exist('edges') ~= 1)
    edges = 'reflect1';
end
if (isstr(filtfile) & (exist(filtfile) == 2))
    [lo0filt,hi0filt,lofilt,bfils,steermtx,harmonics] = eval(filtfile);
else
    fprintf(1,'\nUse buildSpyr for pyramids with arbitrary numbers of orientation
    bands.\n');
    error('FILTFILE argument must be the name of an M-file containing SPYR filters
    .');
end
max_ht = maxPyrHt(size(im), size(lofilt,1));
if ( (exist('ht') ~= 1) | (ht == 'auto') )
    ht = max_ht;
else
    if (ht > max_ht)
        error(sprintf('Cannot build pyramid higher than %d levels.',max_ht));
    end
end
%-----
hi0 = corrDn(im, hi0filt, edges);
lo0 = corrDn(im, lo0filt, edges);
[pyr,pind] = buildSpyrLevs(lo0, ht, lofilt, bfils, edges);
pyr = [hi0(:) ; pyr];
pind = [size(hi0); pind];

```

Apr 16, 98 17:43

buildWpyr.m

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```

% [PYR, INDICES] = buildWpyr(IM, HEIGHT, FILT, EDGES)
%
% Construct a separable orthonormal QMF/wavelet pyramid on matrix (or vector) IM
%
% HEIGHT (optional) specifies the number of pyramid levels to build. Default
% is maxPyrHt(IM,FILT). You can also specify 'auto' to use this value.
%
% FILT (optional) can be a string naming a standard filter (see
% namedFilter), or a vector which will be used for (separable)
% convolution. Filter can be of even or odd length, but should be symmetric.
% Default = 'qmf9'. EDGES specifies edge-handling, and
% defaults to 'reflect1' (see corrDn).
%
% PYR is a vector containing the N pyramid subbands, ordered from fine
% to coarse. INDICES is an Nx2 matrix containing the sizes of
% each subband. This is compatible with the MatLab Wavelet toolbox.
%
% Eroo Simoncelli, 6/96.

function [pyr,pind] = buildWpyr(im, ht, filt, edges)

if (margin < 1)
    error('First argument (IM) is required');
end

%-----
%% OPTIONAL ARGS:

if (exist('filt') ~= 1)
    filt = 'qmf9';
end

if (exist('edges') ~= 1)
    edges = 'reflect1';
end

if isstr(filt)
    filt = namedFilter(filt);
end

if ( (size(filt,1) > 1) & (size(filt,2) > 1) )
    error('FILT should be a 1D filter (i.e., a vector)');
else
    filt = filt(:);
end

hfilt = modulateFlip(filt);

% Stagger sampling if filter is odd-length:
if (mod(size(filt,1),2) == 0)
    stag = 2;
else
    stag = 1;
end

im_sz = size(im);

max_ht = maxPyrHt(im_sz, size(filt,1));
if ( (exist('ht') ~= 1) | (ht == 'auto') )
    ht = max_ht;
else
    if (ht > max_ht)
        error(sprintf('Cannot build pyramid higher than %d levels.',max_ht));
    end
end

if (ht <= 0)

    pyr = im(:);
    pind = im_sz;

else

    if (im_sz(2) == 1)
        lolo = corrDn(im, filt, edges, [2 1], [stag 1]);
        hihi = corrDn(im, hfilt, edges, [2 1], [2 1]);
    elseif (im_sz(1) == 1)
        lolo = corrDn(im, filt, edges, [1 2], [1 stag]);
        hihi = corrDn(im, hfilt, edges, [1 2], [1 2]);
    else
        lo = corrDn(im, filt, edges, [2 1], [stag 1]);
        hi = corrDn(im, hfilt, edges, [2 1], [2 1]);
        lolo = corrDn(lo, filt, edges, [1 2], [1 stag]);
        lohi = corrDn(hi, filt, edges, [1 2], [1 stag]); % horizontal
        hilo = corrDn(lo, hfilt, edges, [1 2], [1 2]); % vertical
        hihi = corrDn(hi, hfilt, edges, [1 2], [1 2]); % diagonal
    end

    [npyr,nind] = buildWpyr(lolo, ht-1, filt, edges);

    if ((im_sz(1) == 1) | (im_sz(2) == 1))
        pyr = [hihi(:); npyr];
        pind = [size(hihi); nind];
    else
        pyr = [lohi(:); hilo(:); hihi(:); npyr];
        pind = [size(lohi); size(hilo); size(hihi); nind];
    end
end
end

```

Apr 26, 97 12:49

cconv2.m

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```

% RES = CCONV2(MTX1, MTX2, CTR)
%
% Circular convolution of two matrices. Result will be of size of
% LARGER vector.
%
% The origin of the smaller matrix is assumed to be its center.
% For even dimensions, the origin is determined by the CTR (optional)
% argument:
%   CTR   origin
%   0     DIM/2     (default)
%   1     (DIM/2)+1
%
% Eroo Simoncelli, 6/96. Modified 2/97.

function c = cconv2(a,b,ctr)

if (exist('ctr') ~= 1)
    ctr = 0;
end

if ((size(a,1) >= size(b,1) ) & ( size(a,2) >= size(b,2) ))
    large = a; small = b;
elseif ((size(a,1) <= size(b,1) ) & ( size(a,2) <= size(b,2) ))
    large = b; small = a;
else
    error('one arg must be larger than the other in both dimensions!');
end

ly = size(large,1);
lx = size(large,2);
sy = size(small,1);
sx = size(small,2);

%% These values are the index of the small mtx that falls on the
%% border pixel of the large matrix when computing the first
%% convolution response sample:
sy2 = floor((sy+ctr+1)/2);
sx2 = floor((sx+ctr+1)/2);

% pad:
clarge = [ ...
    large(ly-sy+sy2+1:ly,lx-sx+sx2+1:lx), large(ly-sy+sy2+1:ly,:), ...
    large(ly-sy+sy2+1:ly,1:sx2-1); ...
    large(:,lx-sx+sx2+1:lx), large, large(:,1:sx2-1); ...
    large(1:sy2-1,lx-sx+sx2+1:lx), ...
    large(1:sy2-1,:), ...
    large(1:sy2-1,1:sx2-1) ];

c = conv2(clarge,small,'valid');

```

Oct 01, 02 17:54

clip.m

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```
% [RES] = clip(IM, MINVALorRANGE, MAXVAL)
%
% Clip values of matrix IM to lie between minVal and maxVal:
%   RES = max(min(IM,MAXVAL),MINVAL)
% The first argument can also specify both min and max, as a 2-vector.
% If only one argument is passed, the range defaults to [0,1].

function res = clip(im, minValOrRange, maxVal)

if (exist('minValOrRange') ~= 1)
    minVal = 0;
    maxVal = 1;
elseif (length(minValOrRange) == 2)
    minVal = minValOrRange(1);
    maxVal = minValOrRange(2);
elseif (length(minValOrRange) == 1)
    minVal = minValOrRange;
    if (exist('maxVal') ~= 1)
        maxVal=minVal+1;
    end
else
    error('MINVAL must be a scalar or a 2-vector');
end

if ( maxVal < minVal )
    error('MAXVAL should be less than MINVAL');
end

res = im;
res(find(im < minVal)) = minVal;
res(find(im > maxVal)) = maxVal;
```

Dec 16, 02 16:16

columnize.m

Page 1/1

```
% [VEC] = columnize(MTX)
%
% Pack elements of MTX into a column vector. Just provides a
% function-call notation for the operation MTX(:)

function vec = columnize(mtx)

vec = mtx(:);
```

May 30, 03 9:15

Contents.m

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```

% Image and Multi-scale Pyramid Tools
% Version 1.2, June 2003.
% Created: Spring, 1996. Eero Simoncelli, eero.simoncelli@nyu.edu
%
% See README file for brief description.
% See ChangeLog file for latest modifications.
% See TUTORIALS subdirectory for demonstrations.
% Type "help <command-name>" for documentation on individual commands.
%-----
% Synthetic Images (matrices):
% mkImpulse - Make an image containing an impulse.
% mkRamp - Make an image containing a ramp function.
% mkR - Make an image containing distance from the origin.
% mkAngle - Make an image containing angle about origin.
% mkDisc - Make an image containing a disk image.
% mkGaussian - Make an image containing a Gaussian function.
% mkZonePlate - Make an image containing a zone plate (cos(r^2)).
% mkAngularSine - Make an image containing an angular sine wave (pinwheel).
% mkSine - Make an image containing a sine grating.
% mkSquare - Make an image containing a square grating.
% mkFract - Make an image containing fractal (1/f) noise.
%
% Point Operations:
% clip - clip values to a range.
% pointOp - Lookup table (much faster than interp1) (MEX file).
% histo - Efficient histogram computation (MEX file).
% histoMatch - Modify matrix elements to match specified histogram stats.
%
% Convolution (first two are significantly faster):
% corrDn - Correlate & downsample with boundary-handling (MEX file).
% upConv - Upsample & convolve with boundary-handling (MEX file).
% blurDn - Blur and subsample a signal/image.
% upBlur - Upsample and blur a signal/image.
% cconv2 - Circular convolution.
% rconv2 - Convolution with reflected boundaries.
% zconv2 - Convolution assuming zeros beyond image boundaries.
%
% General pyramids:
% pyrLow - Access lowpass subband from (any type of) pyramid
% pyrBand - Access a subband from (any type of) pyramid
% setPyrBand - Insert an image into (any type of) pyramid as a subband
% pyrBandIndices - Returns indices for given band in a pyramid vector
% maxPyrHt - compute maximum number of scales in a pyramid
%
% Gaussian/Laplacian Pyramids:
% buildGpyr - Build a Gaussian pyramid of an input signal/image.
% buildLpyr - Build a Laplacian pyramid of an input signal/image.
% reconLpyr - Reconstruct (invert) the Laplacian pyramid transform.
%
% Separable orthonormal QMF/wavelet Pyramids:
% buildWpyr - Build a separable wavelet representation of an input signal/image.
% reconWpyr - Reconstruct (invert) the wavelet transform.
% wpyrBand - Extract a single band of the wavelet representation.
% wpyrLev - Extract (packed) subbands at a particular level
% wpyrHt - Number of levels (height) of a wavelet pyramid.
%
% Steerable Pyramids:
% buildSpyr - Build a steerable pyramid representation of an input image.
% reconSpyr - Reconstruct (invert) the steerable pyramid transform.
% buildSFpyr - Build a steerable pyramid representation in the Fourier domain.
% reconSFpyr - Reconstruct (invert) the (Fourier domain) steerable pyramid transform.
%
% spyrBand - Extract a single band from a steerable pyramid.
% spyrHigh - Highpass residual band.
% spyrLev - A whole level (i.e., all images at a given scale) of a steerable pyramid.
% spyrHt - Number of levels (height) of a steerable pyramid.
% spyrNumBands - Number of orientation bands in a steerable pyramid.
%
% Steerable filters:
% steer - Steer filters (or responses).
% steer2HarmMtx - Construct a matrix mapping directional basis to angular harmonics.
%
% Filters:
% binomialFilter - returns a filter of binomial coefficients.
% namedFilter - some typical Laplacian/Wavelet pyramid filters
% spNFilters - Set of Nth order steerable pyramid filters.
% derivNFiltersS - Matched set of S-tap 1D derivatives, orders 0 to N.
%
% Display:
% showIm - Display a matrix (real or complex) as grayscale image(s). Displays dimensions, subsampling, and range of pixel values.
% showLpyr - Display a Laplacian pyramid.
% showWpyr - Display a separable wavelet pyramid.
% showSpyr - Display a steerable pyramid.
% lplot - "lollipop" plot.
% nextFig - Make next figure window current.
% pixelAxes - Make image display use an integer number of pixels per sample to avoid resampling artifacts.
%
% Statistics (for 2D Matrices):
% range2 - Min and max of image (matrix) (MEX file).
% mean2 - Sample mean of an image (matrix).
% var2 - Sample variance of an image (matrix).
% skew2 - Sample skew (3rd moment / variance^1.5) of an image (matrix).
% kurt2 - Sample kurtosis (4th moment / variance^2) of an image (matrix).
%
% entropy2 - Sample entropy of an image (matrix).
% imStats - Report sample statistics of an image, or pair of images.
%
% Miscellaneous:
% pgmRead - Load a "pgm" image into a MatLab matrix.
% pgmWrite - Write a MatLab matrix to a "pgm" image file.
% shift - circular shift a 2D matrix by an arbitrary amount.
% vectify - pack matrix into column vector (i.e., function to compute mtX(:)).
% ifftshift - inverse of MatLab's FFTSHIFT (differs for odd-length dimensions)
% rcosFn - return a lookup table of a raised-cosine threshold fn.
% innerProd - Compute M'*M (M a matrix) efficiently (i.e., do not copy).

```

Mar 28, 01 10:30

corrDn.m

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```

% RES = corrDn(IM, FILT, EDGES, STEP, START, STOP)
%
% Compute correlation of matrices IM with FILT, followed by
% downsampling. These arguments should be 1D or 2D matrices, and IM
% must be larger (in both dimensions) than FILT. The origin of filt
% is assumed to be floor(size(filt)/2)+1.
%
% EDGES is a string determining boundary handling:
% 'circular' - Circular convolution
% 'reflect1' - Reflect about the edge pixels
% 'reflect2' - Reflect, doubling the edge pixels
% 'repeat' - Repeat the edge pixels
% 'zero' - Assume values of zero outside image boundary
% 'extend' - Reflect and invert
% 'dont-compute' - Zero output when filter overhangs input boundaries
%
% Downsampling factors are determined by STEP (optional, default=[1 1]),
% which should be a 2-vector [y,x].
%
% The window over which the convolution occurs is specified by START
% (optional, default=[1,1], and STOP (optional, default=size(IM)).
%
% NOTE: this operation corresponds to multiplication of a signal
% vector by a matrix whose rows contain copies of the FILT shifted by
% multiples of STEP. See upConv.m for the operation corresponding to
% the transpose of this matrix.
%
% Eero Simoncelli, 6/96, revised 2/97.
%
function res = corrDn(im, filt, edges, step, start, stop)
%
%% NOTE: THIS CODE IS NOT ACTUALLY USED! (MEX FILE IS CALLED INSTEAD)
%
fprintf(1,'WARNING: You should compile the MEX version of "corrDn.c",\n
und in the MEX subdirectory of matlabPyrTools, and put it in your matlab path.
It is MUCH faster, and provides more boundary-handling options.\n');
%-----
%% OPTIONAL ARGS:
%
if (exist('edges') == 1)
    if (strcmp(edges,'reflect1') ~= 1)
        warning('Using REFLECT1 edge-handling (use MEX code for other options).');
    end
end
%
if (exist('step') ~= 1)
    step = [1,1];
end
%
if (exist('start') ~= 1)
    start = [1,1];
end
%
if (exist('stop') ~= 1)
    stop = size(im);
end
%
%-----
% Reverse order of taps in filt, to do correlation instead of convolution
filt = filt(size(filt,1):-1:1,size(filt,2):-1:1);
%
tmp = rconv2(im,filt);
res = tmp(start(1):stop(1),start(2):stop(2):stop(2));

```

Nov 30, 01 22:57

entropy2.m

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```

E = ENTROPY2(MTX,BINSIZE)
%%
%% Compute the first-order sample entropy of MTX. Samples of VEC are
%% first discretized. Optional argument BINSIZE controls the
%% discretization, and defaults to 256/(max(VEC)-min(VEC)).
%%
%% NOTE: This is a heavily biased estimate of entropy when you
%% don't have much data.
%% Bero Simoncelli, 6/96.
function res = entropy2(mtx,binsize)
%% Ensure it's a vector, not a matrix.
vec = mtx(:);
[mn,mx] = range2(vec);
if (exist('binsize') == 1)
    nbins = max((mx-mn)/binsize, 1);
else
    nbins = 256;
end
[bincount,bins] = histo(vec,nbins);
%% Collect non-zero bins:
H = bincount(find(bincount));
H = H/sum(H);
res = -sum(H .* log2(H));

```

Dec 16, 02 16:19

factorial.m

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```

%% RES = factorial(NUM)
%%
%% Factorial function that works on matrices (matlab's does not).
%% EPS, 11/02
function res = factorial(num)
res = ones(size(num));
ind = find(num > 0);
if (~isempty(ind))
    subNum = num(ind);
    res(ind) = subNum .* factorial(subNum-1);
end

```



Mar 28, 01 10:29

histo.m

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```

% [N,X] = histo(MTX, nbinsOrBinsize, binCenter);
%
% Compute a histogram of (all) elements of MTX. N contains the histogram
% counts, X is a vector containing the centers of the histogram bins.
%
% nbinsOrBinsize (optional, default = 101) specifies either
% the number of histogram bins, or the negative of the binsize.
%
% binCenter (optional, default = mean2(MTX)) specifies a center position
% for (any one of) the histogram bins.
%
% How does this differ from MatLab's HIST function? This function:
% - allows uniformly spaced bins only.
% +/- operates on all elements of MTX, instead of columnwise.
% + is much faster (approximately a factor of 80 on my machine).
% + allows specification of number of bins OR binsize. Default=101 bins.
% + allows (optional) specification of binCenter.
%
% Eero Simoncelli, 3/97.

function [N, X] = histo(mtx, nbins, binCtr)

%% NOTE: THIS CODE IS NOT ACTUALLY USED! (MEX FILE IS CALLED INSTEAD)

fprintf(1, 'WARNING: You should compile the MEX version of "histo.c",\n      fou
nd in the MEX subdirectory of matlabPyTools, and put it in your matlab path. I
t is MUCH faster.\n');

mtx = mtx(:);

%-----
%% OPTIONAL ARGS:

[mn,mx] = range2(mtx);

if (exist('binCtr') ~= 1)
    binCtr = mean(mtx);
end

if (exist('nbins') == 1)
    if (nbins < 0)
        binSize = -nbins;
    else
        binSize = ((mx-mn)/nbins);
        tmpNbins = round((mx-binCtr)/binSize) - round((mn-binCtr)/binSize);
        if (tmpNbins ~= nbins)
            warning('Using %d bins instead of requested number (%d)',tmpNbins,nbins);
        end
    end
else
    binSize = ((mx-mn)/101);
end

firstBin = binCtr + binSize*round( (mn-binCtr)/binSize );
tmpNbins = round((mx-binCtr)/binSize) - round((mn-binCtr)/binSize);
bins = firstBin + binSize*[0:tmpNbins];

[N, X] = hist(mtx, bins);

```

May 05, 98 20:59

histoMatch.m

Page 1/1

```

% RES = histoMatch(MTX, N, X)
%
% Modify elements of MTX so that normalized histogram matches that
% specified by vectors X and N, where N contains the histogram counts
% and X the histogram bin positions (see histo).
%
% Eero Simoncelli, 7/96.

function res = histoMatch(mtx, N, X)

if ( exist('histo') == 3 )
    [oN, oX] = histo(mtx(:), size(X(:),1));
else
    [oN, oX] = hist(mtx(:), size(X(:),1));
end

oStep = oX(2) - oX(1);
oC = [0, cumsum(oN)]/sum(oN);
oX = [oX(1)-oStep/2, oX+oStep/2];

N = N(:)';
X = X(:)';
N = N + mean(N)/(1e8); %% HACK: no empty bins ensures nC strictly monotonic

nStep = X(2) - X(1);
nC = [0, cumsum(N)]/sum(N);
nX = [X(1)-nStep/2, X+nStep/2];

nnX = interp1(nC, nX, oC, 'linear');

if ( exist('pointOp') == 3 )
    res = pointOp(mtx, nnX, oX(1), oStep);
else
    res = reshape(interp1(oX, nnX, mtx(:)),size(mtx,1),size(mtx,2));
end

```

Apr 26, 97 12:49

ifftshift.m

Page 1/1

```

% [RES] = ifftshift (MTX)
%
% Inverse of MatLab's FFTSHIFT. That is,
%   ifftshift(fftshift(MTX)) = MTX
%   for any size MTX.
%
% Ero Simoncelli, 2/97.
function [res] = ifftshift(mtx)

sz = size(mtx);
DC = ceil((sz+1)/2);           % location of DC term in a matlab fft.

res = [mtx(DC(1):sz(1), DC(2):sz(2)) , mtx(DC(1):sz(1), 1:DC(2)-1); ...
       mtx(1:DC(1)-1, DC(2):sz(2)) , mtx(1:DC(1)-1, 1:DC(2)-1)];

```

Aug 21, 97 13:39

imStats.m

Page 1/1

```

% imStats(IM1,IM2)
%
% Report image (matrix) statistics.
% When called on a single image IM1, report min, max, mean, stdev,
% and kurtosis.
% When called on two images (IM1 and IM2), report min, max, mean,
% stdev of the difference, and also SNR (relative to IM1).
%
% Ero Simoncelli, 6/96.
function [] = imStats(im1,im2)

if (~isreal(im1))
    error('Args must be real-valued matrices');
end

if (exist('im2') == 1)
    difference = im1 - im2;
    [mn,mx] = range2(difference);
    mean = mean2(difference);
    v = var2(difference,mean);
    if (v < realmin)
        snr = Inf;
    else
        snr = 10 * log10(var2(im1)/v);
    end
    fprintf(1, 'Difference statistics:\n');
    fprintf(1, ' Range: [%c, %c]\n',mn,mx);
    fprintf(1, ' Mean: %f, Stdev (rmse): %f, SNR (dB): %f\n',...
            mean,sqrt(v),snr);
else
    [mn,mx] = range2(im1);
    mean = mean2(im1);
    var = var2(im1);
    stdev = sqrt(real(var))+sqrt(imag(var));
    kurt = kurt2(im1, mean, stdev^2);
    fprintf(1, 'Image statistics:\n');
    fprintf(1, ' Range: [%f, %f]\n',mn,mx);
    fprintf(1, ' Mean: %f, Stdev: %f, Kurtosis: %f\n',mean,stdev,kurt);
end

```

Oct 01, 02 20:54

innerProd.m

Page 1/1

```

% RES = innerProd(MTX)
%
% Compute (MTX' * MTX) efficiently (i.e., without copying the matrix)
function res = innerProd(mtx)
fprintf(1,['WARNING: You should compile the MEX version of' ...
' innerProd.c,\n      found in the MEX subdirectory' ...
' of matlabPyrTools, and put it in your matlab path.' ...
' It is MUCH faster and requires less memory.\n']);
res = mtx' * mtx;

```

Aug 21, 97 13:59

kurt2.m

Page 1/1

```

% K = KURT2(MTX,MEAN,VAR)
%
% Sample kurtosis (fourth moment divided by squared variance)
% of a matrix. Kurtosis of a Gaussian distribution is 3.
% MEAN (optional) and VAR (optional) make the computation faster.
% Eero Simoncelli, 6/96.
function res = kurt2(mtx, mn, v)
if (exist('mn') ~= 1)
    mn = mean(mean(mtx));
end
if (exist('v') ~= 1)
    v = var2(mtx, mn);
end
if (isreal(mtx))
    res = mean(mean(abs(mtx-mn).^4)) / (v^2);
else
    res = mean(mean(real(mtx-mn).^4)) / (real(v)^2) + ...
        i*mean(mean(imag(mtx-mn).^4)) / (imag(v)^2);
end

```

Aug 29, 97 14:24

lplot.m

Page 1/1

```

% lplot(VEC, X RANGE)
%
% Plot VEC, a vector, in "lollipop" format.
% X RANGE (optional, default = [1,length(VEC)]), should be a 2-vector
% specifying the X positions (for labeling purposes) of the first and
% last sample of VEC.

% Mark Liberman, Linguistics Dept, UPenn, 1994.

function lplot(x,xrange)

if (exist('xrange') ~= 1)
    xrange = [1,length(x)];
end

msize = size(x);
if ( msize(2) == 1)
    x = x';
elseif (msize(1) ~= 1)
    error('First arg must be a vector');
end

if (~isreal(x))
    fprintf(1,'Warning: Imaginary part of signal ignored\n');
    x = abs(x);
end

N = length(x);
index = xrange(1) + (xrange(2)-xrange(1))*[0:(N-1)]/(N-1);
xinc = index(2)-index(1);

xx = [zeros(1,N);x;zeros(1,N)];
indexis = [index;index;index];
xdiscrete = [0 xx(:)' 0];
idiscrete = [index(1)-xinc indexis(:)' index(N)+xinc];

[mn,mx] = range2(xdiscrete);
ypad = (mx-mn)/12; % MAGIC NUMBER: graph padding

plot(idiscrete, xdiscrete, index, x, 'o');
axis([index(1)-xinc, index(N)+xinc, mn-ypad, mx+ypad]);

return

```

Apr 26, 97 12:49

lpyrHt.m

Page 1/1

```

% [HEIGHT] = lpyrHt(INDICES)
%
% Compute height of Laplacian pyramid with given its INDICES matrix.
% See buildLpyr.m

% Ero Simoncelli, 6/96.

function [ht] = lpyrHt(pind)

% Don't count lowpass residual band
ht = size(pind,1)-1;

```

Apr 26, 97 12:49

maxPyrHt.m

Page 1/1

```
% HEIGHT = maxPyrHt(IMSIZ, FILTSZ)
%
% Compute maximum pyramid height for given image and filter sizes.
% Specifically: the number of corrDn operations that can be sequentially
% performed when subsampling by a factor of 2.
%
% Ero Simoncelli, 6/96.
function height = maxPyrHt(imsz, filtsz)
imsz = imsz(:);
filtsz = filtsz(:);
if any(imsz == 1) % 1D image
    imsz = prod(imsz);
    filtsz = prod(filtsz);
elseif any(filtsz == 1) % 2D image, 1D filter
    filtsz = [filtsz(1); filtsz(1)];
end
if any(imsz < filtsz)
    height = 0;
else
    height = 1 + maxPyrHt( floor(imsz/2), filtsz );
end
```

Apr 26, 97 12:40

mean2.m

Page 1/1

```
% M = MEAN2(MTX)
%
% Sample mean of a matrix.
function res = mean2(mtx)
res = mean(mean(mtx));
```

Apr 26, 97 12:49

mkAngle.m

Page 1/1

```

% IM = mkAngle(SIZE, PHASE, ORIGIN)
%
% Compute a matrix of dimension SIZE (a [Y X] 2-vector, or a scalar)
% containing samples of the polar angle (in radians, CW from the
% X-axis, ranging from -pi to pi), relative to angle PHASE (default =
% 0), about ORIGIN pixel (default = (size+1)/2).
%
% Ero Simoncelli, 6/96.

function [res] = mkAngle(sz, phase, origin)

sz = sz(:);
if (size(sz,1) == 1)
    sz = [sz,sz];
end

% -----
% OPTIONAL args:

if (exist('origin') ~= 1)
    origin = (sz+1)/2;
end

% -----

[xramp,yramp] = meshgrid( [1:sz(2)]-origin(2), [1:sz(1)]-origin(1) );
res = atan2(yramp,xramp);

if (exist('phase') == 1)
    res = mod(res+(pi-phase),2*pi)-pi;
end

```

Apr 26, 97 12:49

mkAngularSine.m

Page 1/1

```

% IM = mkAngularSine(SIZE, HARMONIC, AMPL, PHASE, ORIGIN)
%
% Make an angular sinusoidal image:
%   AMPL * sin(HARMONIC*theta + PHASE),
% where theta is the angle about the origin.
% SIZE specifies the matrix size, as for zeros().
% AMPL (default = 1) and PHASE (default = 0) are optional.
%
% Ero Simoncelli, 2/97.

function [res] = mkAngularSine(sz, harmonic, ampl, ph, origin)

sz = sz(:);
if (size(sz,1) == 1)
    sz = [sz,sz];
end

mxsz = max(sz(1),sz(2));

% -----
% OPTIONAL ARGS:

if (exist('harmonic') ~= 1)
    harmonic = 1;
end

if (exist('ampl') ~= 1)
    ampl = 1;
end

if (exist('ph') ~= 1)
    ph = 0;
end

if (exist('origin') ~= 1)
    origin = (sz+1)/2;
end

% -----

res = ampl * sin(harmonic*mkAngle(sz,ph,origin) + ph);

```

Apr 26, 97 12:49

mkDisc.m

Page 1/1

```

% IM = mkDisc(SIZE, RADIUS, ORIGIN, TWIDTH, VALS)
%
% Make a "disk" image. SIZE specifies the matrix size, as for
% zeros(). RADIUS (default = min(size)/4) specifies the radius of
% the disk. ORIGIN (default = (size+1)/2) specifies the
% location of the disk center. TWIDTH (in pixels, default = 2)
% specifies the width over which a soft threshold transition is made.
% VALS (default = [0,1]) should be a 2-vector containing the
% intensity value inside and outside the disk.
%
% Ero Simoncelli, 6/96.

function [res] = mkDisc(sz, rad, origin, twidth, vals)

if (nargin < 1)
    error('Must pass at least a size argument');
end

sz = sz(:);
if (size(sz,1) == 1)
    sz = [sz sz];
end

%-----
% OPTIONAL ARGS:
if (exist('rad') ~= 1)
    rad = min(sz(1),sz(2))/4;
end

if (exist('origin') ~= 1)
    origin = (sz+1)./2;
end

if (exist('twidth') ~= 1)
    twidth = 2;
end

if (exist('vals') ~= 1)
    vals = [1,0];
end

%-----
res = mkR(sz,1,origin);

if (abs(twidth) < realmin)
    res = vals(2) + (vals(1) - vals(2)) * (res <= rad);
else
    [Xtbl,Ytbl] = rcosFn(twidth, rad, [vals(1), vals(2)]);
    res = pointOp(res, Ytbl, Xtbl(1), Xtbl(2)-Xtbl(1), 0);
end

% OLD interp1 VERSION:
% res = res(:);
% Xtbl(1) = min(res);
% Xtbl(size(Xtbl,2)) = max(res);
% res = reshape(interp1(Xtbl,Ytbl,res), sz(1), sz(2));
end

```

Apr 26, 97 12:50

mkFract.m

Page 1/1

```

% IM = mkFract(SIZE, FRACT_DIM)
%
% Make a matrix of dimensions SIZE (a [Y X] 2-vector, or a scalar)
% containing fractal (pink) noise with power spectral density of the
% form: 1/f^(5-2*FRACT_DIM). Image variance is normalized to 1.0.
% FRACT_DIM defaults to 1.0
%
% Ero Simoncelli, 6/96.

%% TODO: Verify that this matches Mandelbrot defn of fractal dimension.
%% Make this more efficient!

function res = mkFract(dims, fract_dim)

if (exist('fract_dim') ~= 1)
    fract_dim = 1.0;
end

res = randn(dims);
fres = fft2(res);

sz = size(res);
ctr = ceil((sz+1)./2);

shape = ifftshift(mkR(sz, -(2.5-fract_dim), ctr));
shape(1,1) = 1; %DC term

fres = shape .* fres;
fres = ifft2(fres);

if (max(max(abs(imag(fres)))) > 1e-10)
    error('Symmetry error in creating fractal');
else
    res = real(fres);
    res = res / sqrt(var2(res));
end

```

Apr 28, 97 22:32

mkGaussian.m

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```

% IM = mkGaussian(SIZE, COVARIANCE, MEAN, AMPLITUDE)
%
% Compute a matrix with dimensions SIZE (a [Y X] 2-vector, or a
% scalar) containing a Gaussian function, centered at pixel position
% specified by MEAN (default = (size+1)/2), with given COVARIANCE (can
% be a scalar, 2-vector, or 2x2 matrix. Default = (min(size)/6)^2),
% and AMPLITUDE. AMPLITUDE='norm' (default) will produce a
% probability-normalized function. All but the first argument are
% optional.

% Eero Simoncelli, 6/96.

function [res] = mkGaussian(sz, cov, mn, ampl)

sz = sz(:);
if (size(sz,1) == 1)
    sz = [sz,sz];
end

%-----
%% OPTIONAL ARGS:
if (exist('cov') ~= 1)
    cov = (min(sz(1),sz(2))/6)^2;
end

if (exist('mn') ~= 1)
    mn = (sz+1)/2;
end

if (exist('ampl') ~= 1)
    ampl = 'norm';
end

%-----

[xramp,yramp] = meshgrid([1:sz(2)]-mn(2),[1:sz(1)]-mn(1));

if (sum(size(cov)) == 2) % scalar
    if (strcmp(ampl,'norm'))
        ampl = 1/(2*pi*cov(1));
    end
    e = (xramp.^2 + yramp.^2)/(-2 * cov);
elseif (sum(size(cov)) == 3) % a 2-vector
    if (strcmp(ampl,'norm'))
        ampl = 1/(2*pi*sqrt(cov(1)*cov(2)));
    end
    e = xramp.^2/(-2 * cov(2)) + yramp.^2/(-2 * cov(1));
else
    if (strcmp(ampl,'norm'))
        ampl = 1/(2*pi*sqrt(det(cov)));
    end
    cov = -inv(cov)/2;
    e = cov(2,2)*xramp.^2 + (cov(1,2)+cov(2,1))*(xramp.*yramp) ...
        + cov(1,1)*yramp.^2;
end

res = ampl .* exp(e);

```

Apr 26, 97 12:50

mkImpulse.m

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```

% IM = mkImpulse(SIZE, ORIGIN, AMPLITUDE)
%
% Compute a matrix of dimension SIZE (a [Y X] 2-vector, or a scalar)
% containing a single non-zero entry, at position ORIGIN (defaults to
% ceil(size/2)), of value AMPLITUDE (defaults to 1).

% Eero Simoncelli, 6/96.

function [res] = mkImpulse(sz, origin, amplitude)

sz = sz(:);
if (size(sz,2) == 1)
    sz = [sz sz];
end

if (exist('origin') ~= 1)
    origin = ceil(sz/2);
end

if (exist('amplitude') ~= 1)
    amplitude = 1;
end

res = zeros(sz);
res(origin(1),origin(2)) = amplitude;

```



Apr 26, 97 12:50

mkRamp.m

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```

% IM = mkRamp(SIZE, DIRECTION, SLOPE, INTERCEPT, ORIGIN)
%
% Compute a matrix of dimension SIZE (a [Y X] 2-vector, or a scalar)
% containing samples of a ramp function, with given gradient DIRECTION
% (radians, CW from X-axis, default = 0), SLOPE (per pixel, default =
% 1), and a value of INTERCEPT (default = 0) at the ORIGIN (default =
% (size+1)/2, [1 1] = upper left). All but the first argument are
% optional.

% Ero Simoncelli, 6/96. 2/97: adjusted coordinate system.

function [res] = mkRamp(sz, dir, slope, intercept, origin)

sz = sz(:);
if (size(sz,1) == 1)
    sz = [sz,sz];
end

% -----
% OPTIONAL args:
if (exist('dir') ~= 1)
    dir = 0;
end

if (exist('slope') ~= 1)
    slope = 1;
end

if (exist('intercept') ~= 1)
    intercept = 0;
end

if (exist('origin') ~= 1)
    origin = (sz+1)/2;
end

% -----

xinc = slope*cos(dir);
yinc = slope*sin(dir);

[xramp,yramp] = meshgrid( xinc*(1:sz(2))-origin(2), ...
    yinc*(1:sz(1))-origin(1) );

res = intercept + xramp + yramp;

```

Apr 26, 97 12:50

mkR.m

Page 1/1

```

% IM = mkR(SIZE, EXPT, ORIGIN)
%
% Compute a matrix of dimension SIZE (a [Y X] 2-vector, or a scalar)
% containing samples of a radial ramp function, raised to power EXPT
% (default = 1), with given ORIGIN (default = (size+1)/2, [1 1] =
% upper left). All but the first argument are optional.

% Ero Simoncelli, 6/96.

function [res] = mkR(sz, expt, origin)

sz = sz(:);
if (size(sz,1) == 1)
    sz = [sz,sz];
end

% -----
% OPTIONAL args:
if (exist('expt') ~= 1)
    expt = 1;
end

if (exist('origin') ~= 1)
    origin = (sz+1)/2;
end

% -----

[xramp,yramp] = meshgrid( [1:sz(2)]-origin(2), [1:sz(1)]-origin(1) );

res = (xramp.^2 + yramp.^2).^(expt/2);

```

Apr 26, 97 12:50

mkSine.m

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```

% IM = mkSine(SIZE, PERIOD, DIRECTION, AMPLITUDE, PHASE, ORIGIN)
% or
% IM = mkSine(SIZE, FREQ, AMPLITUDE, PHASE, ORIGIN)
%
% Compute a matrix of dimension SIZE (a [Y X] 2-vector, or a scalar)
% containing samples of a 2D sinusoid, with given PERIOD (in pixels),
% DIRECTION (radians, CW from X-axis, default = 0), AMPLITUDE (default
% = 1), and PHASE (radians, relative to ORIGIN, default = 0). ORIGIN
% defaults to the center of the image.
%
% In the second form, FREQ is a 2-vector of frequencies (radians/pixel).
%
% Eero Simoncelli, 6/96.

function [res] = mkSine(sz, per_freq, dir_amp, amp_phase, phase_orig, orig)
%-----
%% OPTIONAL ARGS:

if (prod(size(per_freq)) == 2)
    frequency = norm(per_freq);
    direction = atan2(per_freq(1),per_freq(2));
    if (exist('dir_amp') == 1)
        amplitude = dir_amp;
    else
        amplitude = 1;
    end
    if (exist('amp_phase') == 1)
        phase = amp_phase;
    else
        phase = 0;
    end
    if (exist('phase_orig') == 1)
        origin = phase_orig;
    end
    if (exist('orig') == 1)
        error('Too many arguments for (second form) of mkSine');
    end
else
    frequency = 2*pi/per_freq;
    if (exist('dir_amp') == 1)
        direction = dir_amp;
    else
        direction = 0;
    end
    if (exist('amp_phase') == 1)
        amplitude = amp_phase;
    else
        amplitude = 1;
    end
    if (exist('phase_orig') == 1)
        phase = phase_orig;
    else
        phase = 0;
    end
    if (exist('orig') == 1)
        origin = orig;
    end
end

%-----

if (exist('origin') == 1)
    res = amplitude*sin(mkRamp(sz, direction, frequency, phase, origin));
else
    res = amplitude*sin(mkRamp(sz, direction, frequency, phase));
end

```

Oct 13, 97 14:51

mkSquare.m

Page 1/1

```

% IM = mkSquare(SIZE, PERIOD, DIRECTION, AMPLITUDE, PHASE, ORIGIN, TWIDTH)
% or
% IM = mkSquare(SIZE, FREQ, AMPLITUDE, PHASE, ORIGIN, TWIDTH)
%
% Compute a matrix of dimension SIZE (a [Y X] 2-vector, or a scalar)
% containing samples of a 2D square wave, with given PERIOD (in
% pixels), DIRECTION (radians, CW from X-axis, default = 0), AMPLITUDE
% (default = 1), and PHASE (radians, relative to ORIGIN, default = 0).
% ORIGIN defaults to the center of the image. TWIDTH specifies width
% of raised-cosine edges on the bars of the grating (default =
% min(2,period/3)).
%
% In the second form, FREQ is a 2-vector of frequencies (radians/pixel).
%
% Eero Simoncelli, 6/96.

% TODO: Add duty cycle.

function [res] = mkSquare(sz, per_freq, dir_amp, amp_phase, phase_orig, orig_twidth, twidth)
%-----
%% OPTIONAL ARGS:

if (prod(size(per_freq)) == 2)
    frequency = norm(per_freq);
    direction = atan2(per_freq(1),per_freq(2));
    if (exist('dir_amp') == 1)
        amplitude = dir_amp;
    else
        amplitude = 1;
    end
    if (exist('amp_phase') == 1)
        phase = amp_phase;
    else
        phase = 0;
    end
    if (exist('phase_orig') == 1)
        origin = phase_orig;
    end
    if (exist('orig_twidth') == 1)
        transition = orig_twidth;
    else
        transition = min(2,2*pi/(3*frequency));
    end
    if (exist('twidth') == 1)
        error('Too many arguments for (second form) of mkSquare');
    end
else
    frequency = 2*pi/per_freq;
    if (exist('dir_amp') == 1)
        direction = dir_amp;
    else
        direction = 0;
    end
    if (exist('amp_phase') == 1)
        amplitude = amp_phase;
    else
        amplitude = 1;
    end
    if (exist('phase_orig') == 1)
        phase = phase_orig;
    else
        phase = 0;
    end
    if (exist('orig_twidth') == 1)
        origin = orig_twidth;
    end
    if (exist('twidth') == 1)
        transition = twidth;
    else
        transition = min(2,2*pi/(3*frequency));
    end
end

end

%-----

if (exist('origin') == 1)
    res = mkRamp(sz, direction, frequency, phase, origin) - pi/2;
else
    res = mkRamp(sz, direction, frequency, phase) - pi/2;
end

[Xtbl,Ytbl] = rcosFn(transition*frequency,pi/2,[-amplitude amplitude]);
res = pointOp(abs(mod(res+pi, 2*pi)-pi),Ytbl,Xtbl(1),Xtbl(2)-Xtbl(1),0);

% OLD threshold version:
%res = amplitude * (mod(res,2*pi) < pi);

```

Apr 26, 97 12:50

mkZonePlate.m

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```

% IM = mkZonePlate(SIZE, AMPL, PHASE)
%
% Make a "zoneplate" image:
%   AMPL * cos( r^2 + PHASE)
% SIZE specifies the matrix size, as for zeros().
% AMPL (default = 1) and PHASE (default = 0) are optional.
% Ero Simoncelli, 6/96.

function [res] = mkZonePlate(sz, ampl, ph)

sz = sz(:);
if (size(sz,1) == 1)
    sz = [sz,sz];
end

mxsz = max(sz(1),sz(2));

%-----
%% OPTIONAL ARGS:

if (exist('ampl') ~= 1)
    ampl = 1;
end

if (exist('ph') ~= 1)
    ph = 0;
end

%-----

res = ampl * cos( (pi/mxsz) * mkR(sz,2) + ph );

```

Jan 30, 98 14:03

mod.m

Page 1/1

```

% M = mod(A,B)
%
% Modulus operator: returns A mod B.
% Works on matrices, vectors or scalars.
%
% NOTE: This function is a Matlab-5 builtin, but was missing from Matlab-4.
% Ero Simoncelli, 7/96.

function m = mod(a,n)

m = a - n .* floor(a./n);
return;

```

Apr 26, 97 12:50

modulateFlip.m

Page 1/1

```

% [HFILT] = modulateFlipShift(LFILT)
%
% QMF/Wavelet highpass filter construction: modulate by (-1)^n,
% reverse order (and shift by one, which is handled by the convolution
% routines). This is an extension of the original definition of QMF's
% (e.g., see Simoncelli90).
%
% Ero Simoncelli, 7/96.
function [hfilt] = modulateFlipShift(lfilt)
lfilt = lfilt(:);
sz = size(lfilt,1);
sz2 = ceil(sz/2);
ind = [sz:-1:1]';
hfilt = lfilt(ind) .* (-1).^(ind-sz2);

```

Apr 26, 97 12:50

namedFilter.m

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```

% KERNEL = NAMED_FILTER(NAME)
%
% Some standard 1D filter kernels. These are scaled such that
% their L2-norm is 1.0.
%
% binomN - binomial coefficient filter of order N-1
% haar: - Haar wavelet.
% qmf8, qmf12, qmf16 - Symmetric Quadrature Mirror Filters [Johnston80]
% daub2, daub3, daub4 - Daubechies wavelet [Daubechies88].
% qmf5, qmf9, qmf13: - Symmetric Quadrature Mirror Filters [Simoncelli88, Simon
% elli90]
%
% See bottom of file for full citations.
%
% Ero Simoncelli, 6/96.
function [kernel] = named_filter(name)
if strcmp(name(1:min(5,size(name,2))), 'binom')
kernel = sqrt(2) * binomialFilter(str2num(name(6:size(name,2))));
elseif strcmp(name, 'qmf5')
kernel = [-0.076103 0.3535534 0.8593118 0.3535534 -0.076103]';
elseif strcmp(name, 'qmf9')
kernel = [0.02807382 -0.060944743 -0.073386624 0.41472545 0.7973934 ...
0.41472545 -0.073386624 -0.060944743 0.02807382]';
elseif strcmp(name, 'qmf13')
kernel = [-0.014556438 0.021651438 0.039045125 -0.09800052 ...
-0.057827797 0.42995453 0.7737113 0.42995453 -0.057827797 ...
-0.09800052 0.039045125 0.021651438 -0.014556438]';
elseif strcmp(name, 'qmf8')
kernel = sqrt(2) * [0.00938715 -0.07065183 0.06942827 0.4899808 ...
0.4899808 0.06942827 -0.07065183 0.00938715 ]';
elseif strcmp(name, 'qmf12')
kernel = sqrt(2) * [-0.003809699 0.01885659 -0.002710326 -0.08469594 ...
0.08846992 0.4843894 0.4843894 0.08846992 -0.08469594 -0.002710326 ...
0.01885659 -0.003809699 ]';
elseif strcmp(name, 'qmf16')
kernel = sqrt(2) * [0.001050167 -0.005054526 -0.002589756 0.0276414 -0.0096663
76 ...
-0.09039223 0.09779817 0.4810284 0.4810284 0.09779817 -0.09039223 -0.009
666376 ...
0.0276414 -0.002589756 -0.005054526 0.001050167 ]';
elseif strcmp(name, 'haar')
kernel = [1 1] / sqrt(2);
elseif strcmp(name, 'daub2')
kernel = [0.482962913145 0.836516303738 0.224143868042 -0.129409522551]';
elseif strcmp(name, 'daub3')
kernel = [0.332670552950 0.806891509311 0.459877502118 -0.135011020010 ...
-0.085441273882 0.035226291882]';
elseif strcmp(name, 'daub4')
kernel = [0.230377813309 0.714846570553 0.630880767930 -0.027983769417 ...
-0.187034811719 0.030841381836 0.032883011667 -0.010597401785]';
elseif strcmp(name, 'gauss5') % for backward-compatibility
kernel = sqrt(2) * [0.0625 0.25 0.375 0.25 0.0625]';
elseif strcmp(name, 'gauss3') % for backward-compatibility
kernel = sqrt(2) * [0.25 0.5 0.25]';
else
error(sprintf('Bad filter name: %s\n', name));
end
%
% [Johnston80] - J D Johnston, "A filter family designed for use in quadrature
% mirror filter banks", Proc. ICASSP, pp 291-294, 1980.
%
% [Daubechies88] - I Daubechies, "Orthonormal bases of compactly supported wavelets",
% Commun. Pure Appl. Math, vol. 42, pp 909-996, 1988.
%
% [Simoncelli88] - E P Simoncelli, "Orthogonal sub-band image transforms",
% PhD Thesis, MIT Dept. of Elec. Eng. and Comp. Sci. May 1988.
% Also available as: MIT Media Laboratory Vision and Modeling Technical
% Report #100.
%
% [Simoncelli90] - E P Simoncelli and E H Adelson, "Subband image coding",
% Subband Transforms, chapter 4, ed. John W Woods, Kluwer Academic
% Publishers, Norwell, MA, 1990, pp 143--192.

```

Apr 26, 97 12:50

nextFig.m

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```

% nextFig (MAXFIGS, SKIP)
%
% Make figure number mod((GCF+SKIP), MAXFIGS) the current figure.
% MAXFIGS is optional, and defaults to 2.
% SKIP is optional, and defaults to 1.

% Eero Simoncelli, 2/97.

function nextFig(maxfigs, skip)

if (exist('maxfigs') ~= 1)
    maxfigs = 2;
end

if (exist('skip') ~= 1)
    skip = 1;
end

figure(1+mod(gcf-1+skip,maxfigs));

```

May 10, 97 14:43

pgmRead.m

Page 1/1

```

% IM = pgmRead( FILENAME )
%
% Load a pgm image into a MatLab matrix.
% This format is accessible from the XV image browsing utility.
% Only works for 8bit gray images (raw or ascii)

% Hany Farid, Spring '96. Modified by Eero Simoncelli, 6/96.

function im = pgmRead( fname );

[fid,msg] = fopen( fname, 'r' );

if (fid == -1)
    error(msg);
end

%%% First line contains ID string:
%%% "P1" = ascii bitmap, "P2" = ascii greymap,
%%% "P3" = ascii pixmap, "P4" = raw bitmap,
%%% "P5" = raw greymap, "P6" = raw pixmap
TheLine = fgetl(fid);
format = TheLine;

if ~(format(1:2) == 'P2' | (format(1:2) == 'P5'))
    error('PGM file must be of type P2 or P5');
end

%%% Any number of comment lines
TheLine = fgetl(fid);
while TheLine(1) == '#'
    TheLine = fgetl(fid);
end

%%% dimensions
sz = sscanf(TheLine, '%d', 2);
xdim = sz(1);
ydim = sz(2);
sz = xdim * ydim;

%%% Maximum pixel value
TheLine = fgetl(fid);
maxval = sscanf(TheLine, '%d', 1);

%%im = zeros(dim,1);
if (format(2) == '2')
    [im,count] = fscanf(fid, '%d', sz);
else
    [im,count] = fread(fid, sz, 'uchar');
end

fclose(fid);

if (count == sz)
    im = reshape( im, xdim, ydim );
else
    fprintf(1, 'Warning: File ended early!');
    im = reshape( [im ; zeros(sz-count,1)], xdim, ydim );
end

```

```

Apr 16, 98 18:10          pgmWrite.m          Page 1/1
% RANGE = pgmWrite(MTX, FILENAME, RANGE, TYPE, COMMENT)
%
% Write a MatLab matrix to a pgm (graylevel image) file.
% This format is accessible from the XV image browsing utility.
%
% RANGE (optional) is a 2-vector specifying the values that map to
% black and white, respectively. Passing a value of 'auto' (default)
% sets RANGE=[min,max] (as in MatLab's imagesc). 'auto2' sets
% RANGE=[mean-2*stdev, mean+2*stdev]. 'auto3' sets
% RANGE=[p1-(p2-p1)/8, p2+(p2-p1)/8], where p1 is the 10th percentile
% value of the sorted MATRIX samples, and p2 is the 90th percentile
% value.
%
% TYPE (optional) should be 'raw' or 'ascii'. Defaults to 'raw'.
%
% Hany Farid, Spring '96. Modified by Eero Simoncelli, 6/96.

function range = pgmWrite(mtx, fname, range, type, comment );

[fid,msg] = fopen( fname, 'w' );

if (fid == -1)
    error(msg);
end

%-----
%% optional ARGS:

if (exist('range') ~= 1)
    range = 'auto';
end

if (exist('type') ~= 1)
    type = 'raw';
end

%-----
%% Automatic range calculation:
if (strcmp(range,'auto1') | strcmp(range,'auto'))
    [mn,mx] = range2(mtx);
    range = [mn,mx];
elseif strcmp(range,'auto2')
    stdev = sqrt(var2(mtx));
    av = mean2(mtx);
    range = [av-2*stdev,av+2*stdev];    % MAGIC NUMBER: 2 stdevs
elseif strcmp(range,'auto3')
    percentile = 0.1;    % MAGIC NUMBER: 0<p<0.5
    [N,X] = histo(mtx);
    binsz = X(2)-X(1);
    N = N+1e-10;    % Ensure cumsum will be monotonic for call to interp1
    cumN = [0, cumsum(N)]/sum(N);
    cumX = [X(1)-binsz, X] + (binsz/2);
    ctrRange = interp1(cumN,cumX, [percentile, 1-percentile]);
    range = mean(ctrRange) + (ctrRange-mean(ctrRange))/(1-2*percentile);
elseif isstr(range)
    error(sprintf('Bad RANGE argument: %s',range))
end

if ((range(2) - range(1)) <= eps)
    range(1) = range(1) - 0.5;
    range(2) = range(2) + 0.5;
end

%%% First line contains ID string:
%%% "P1" = ascii bitmap, "P2" = ascii greymap,
%%% "P3" = ascii pixmap, "P4" = raw bitmap,
%%% "P5" = raw greymap, "P6" = raw pixmap
if strcmp(type,'raw')
    fprintf(fid,'P5\n');
    format = 5;
elseif strcmp(type,'ascii')
    fprintf(fid,'P2\n');
    format = 2;
else
    error(sprintf('PGMWRITE: Bad type argument: %s',type));
end

fprintf(fid,'# MatLab PGMWRITE file, saved %s\n',date);

if (exist('comment') == 1)
    fprintf(fid,'# %s\n', comment);
end

%%% dimensions
fprintf(fid,'%d %d\n',size(mtx,2),size(mtx,1));

%%% Maximum pixel value
fprintf(fid,'255\n');

% MatLab's "fprintf" floors when writing floats, so we compute
% (mtx-r1)*255/(r2-r1)+0.5
mult = (255 / (range(2)-range(1)));
mtx = (mult * mtx) + (0.5 - mult * range(1));

mtx = max(-0.5+eps,min(255.5-eps,mtx));

if (format == 2)
    count = fprintf(fid,'%d ',mtx');
elseif (format == 5)
    count = fwrite(fid,mtx','uchar');
end

fclose(fid);

if (count ~= size(mtx,1)*size(mtx,2))
    fprintf(1,'Warning: File output terminated early!');
end

%%% TEST:
% foo = 257*rand(100)-1;
% pgmWrite(foo,'foo.pgm',[0 255]);
% foo2=pgmRead('foo.pgm');
% size(find((foo2-round(foo))~=0))
% foo(find((foo2-round(foo))~=0))

```

```

Feb 17, 98 15:01          pixelAxes.m          Page 1/1
% [ZOOM] = pixelAxes(DIMS, ZOOM)
%
% Set the axes of the current plot to cover a multiple of DIMS pixels,
% thereby eliminating screen aliasing artifacts when displaying an
% image of size DIMS.
%
% ZOOM (optional, default='same') expresses the desired number of
% samples displayed per screen pixel. It should be a scalar, which
% will be rounded to the nearest integer, or 1 over an integer. It
% may also be the string 'same' or 'auto', in which case the value is chosen so
% as to produce an image closest in size to the currently displayed
% image. It may also be the string 'full', in which case the image is
% made as large as possible while still fitting in the window.
%
% Eero Simoncelli, 2/97.

function [zoom] = pixelAxes(dims, zoom)

%-----
%% OPTIONAL ARGS:

if (exist('zoom') ~= 1)
    zoom = 'same';
end

%% Reverse dimension order, since Figure Positions reported as (x,y).
dims = dims(2:-1:1);

%% Use MatLab's axis function to force square pixels, etc:
axis('image');
ax = gca;

oldunits = get(ax,'Units');

if strcmp(zoom,'full');
    set(ax,'Units','normalized');
    set(ax,'Position',[0 0 1 1]);
    zoom = 'same';
end

set(ax,'Units','pixels');
pos = get(ax,'Position');
ctr = pos(1:2)+pos(3:4)/2;

if (strcmp(zoom,'same') | strcmp(zoom,'auto'))
    %% HACK: enlarge slightly so that floor doesn't round down
    zoom = min( pos(3:4) ./ (dims - 1) );
elseif isstr(zoom)
    error(sprintf('Bad ZOOM argument: %s',zoom));
end

%% Force zoom value to be an integer, or inverse integer.
if (zoom < 0.75)
    zoom = 1/ceil(1/zoom);
    %% Round upward, subtracting 0.5 to avoid floating point errors.
    newsz = ceil(zoom*(dims-0.5));
else
    zoom = floor(zoom + 0.001);    % Avoid floating pt errors
    if (zoom < 1.5)    % zoom=1
        zoom = 1;
        newsz = dims + 0.5;
    else
        newsz = zoom*(dims-1) + mod(zoom,2);
    end
end

set(ax,'Position', [floor(ctr-newsz/2)+0.5, newsz] )

% Restore units
set(ax,'Units',oldunits);

```

Sep 18, 02 18:09

pointOp.m

Page 1/1

```

% RES = pointOp(IM, LUT, ORIGIN, INCREMENT, WARNINGS)
%
% Apply a point operation, specified by lookup table LUT, to image IM.
% LUT must be a row or column vector, and is assumed to contain
% (equi-spaced) samples of the function. ORIGIN specifies the
% abscissa associated with the first sample, and INCREMENT specifies the
% spacing between samples. Between-sample values are estimated via
% linear interpolation. If WARNINGS is non-zero, the function prints
% a warning whenever the lookup table is extrapolated.
%
% This function is much faster than MatLab's interp1, and allows
% extrapolation beyond the lookup table domain. The drawbacks are
% that the lookup table must be equi-spaced, and the interpolation is
% linear.
%
% Ero Simoncelli, 8/96.

function res = pointOp(im, lut, origin, increment, warnings)

%% NOTE: THIS CODE IS NOT ACTUALLY USED! (MEX FILE IS CALLED INSTEAD)

fprintf(1,'WARNING: You should compile the MEX version of "pointOp.c",\n f
ound in the MEX subdirectory of matlabPyrTools, and put it in your matlab path.
It is MUCH faster.\n');

X = origin + increment*[0:size(lut(:),1)-1];
Y = lut(:);

res = reshape(interp1(X, Y, im(:), 'linear', 'extrap'),size(im));

```

Jul 17, 96 1:30

pwd2path.m

Page 1/1

```

% PWD2PATH()
%
% add current working directory (pwd) to path.

P = path;
path(pwd,P);

```

Jun 20, 97 19:30 **pyrBandIndices.m** Page 1/1

```

% RES = pyrBandIndices(INDICES, BAND_NUM)
%
% Return indices for accessing a subband from a pyramid
% (gaussian, laplacian, QMF/wavelet, steerable).
% Ero Simoncelli, 6/96.
function indices = pyrBandIndices(pind,band)
if ((band > size(pind,1)) | (band < 1))
    error(sprintf('BAND_NUM must be between 1 and number of pyramid bands (%d).',
    ...
    size(pind,1)));
end
if (size(pind,2) ~= 2)
    error('INDICES must be an Nx2 matrix indicating the size of the pyramid subbands');
end
ind = 1;
for l=1:band-1
    ind = ind + prod(pind(1,:));
end
indices = ind:ind+prod(pind(band,:))-1;

```

Dec 17, 97 10:10 **pyrBand.m** Page 1/1

```

% RES = pyrBand(PYR, INDICES, BAND_NUM)
%
% Access a subband from a pyramid (gaussian, laplacian, QMF/wavelet,
% or steerable). Subbands are numbered consecutively, from finest
% (highest spatial frequency) to coarsest (lowest spatial frequency).
% Ero Simoncelli, 6/96.
function res = pyrBand(pyr, pind, band)
res = reshape( pyr(pyrBandIndices(pind,band)), pind(band,1), pind(band,2) );

```



Apr 26, 97 12:50

pyrLow.m

Page 1/1

```

% RES = pyrLow(PYR, INDICES)
%
% Access the lowpass subband from a pyramid
% (gaussian, laplacian, QMF/wavelet, steerable).
%
% Ero Simoncelli, 6/96.
function res = pyrLow(pyr,pind)
band = size(pind,1);
res = reshape( pyr(pyrBandIndices(pind,band)), pind(band,1), pind(band,2) );

```

Mar 28, 01 10:31

range2.m

Page 1/1

```

% [MIN, MAX] = range2(MTX)
%
% Compute minimum and maximum values of MTX, returning them as a 2-vector.
%
% Ero Simoncelli, 3/97.
function [mn, mx] = range2(mtx)
%% NOTE: THIS CODE IS NOT ACTUALLY USED! (MEX FILE IS CALLED INSTEAD)
fprintf(1,'WARNING: You should compile the MEX version of "range2.c",\n fo
und in the MEX subdirectory of matlabPyrTools, and put it in your matlab path.
It is MUCH faster.\n');
if (~isreal(mtx))
    error('MTX must be real-valued');
end
mn = min(min(mtx));
mx = max(max(mtx));

```

Apr 26, 97 12:50

rconv2.m

Page 1/1

```

% RES = RCONV2(MTX1, MTX2, CTR)
%
% Convolution of two matrices, with boundaries handled via reflection
% about the edge pixels. Result will be of size of LARGER matrix.
%
% The origin of the smaller matrix is assumed to be its center.
% For even dimensions, the origin is determined by the CTR (optional)
% argument:
%   CTR   origin
%   0     DIM/2   (default)
%   1     (DIM/2)+1
%
% Eero Simoncelli, 6/96.

function c = rconv2(a,b,ctr)

if (exist('ctr') ~= 1)
    ctr = 0;
end

if ((size(a,1) >= size(b,1) ) & ( size(a,2) >= size(b,2) ))
    large = a; small = b;
elseif (( size(a,1) <= size(b,1) ) & ( size(a,2) <= size(b,2) ))
    large = b; small = a;
else
    error('one arg must be larger than the other in both dimensions!');
end

ly = size(large,1);
lx = size(large,2);
sy = size(small,1);
sx = size(small,2);

%% These values are one less than the index of the small mtx that falls on
%% the border pixel of the large matrix when computing the first
%% convolution response sample:
sy2 = floor((sy+ctr-1)/2);
sx2 = floor((sx+ctr-1)/2);

% pad with reflected copies
clarge = [
    large(sy-sy2:-1:2,sx-sx2:-1:2), large(sy-sy2:-1:2,:), ...
    large(sy-sy2:-1:2,lx-1:-1:lx-sx2); ...
    large(:,sx-sx2:-1:2), large, large(:,lx-1:-1:lx-sx2); ...
    large(lx-1:-1:ly-sy2,sx-sx2:-1:2), ...
    large(ly-1:-1:ly-sy2,:), ...
    large(ly-1:-1:ly-sy2,lx-1:-1:lx-sx2) ];

c = conv2(clarge,small,'valid');

```

Oct 07, 97 12:11

rcosFn.m

Page 1/1

```

% [X, Y] = rcosFn(WIDTH, POSITION, VALUES)
%
% Return a lookup table (suitable for use by INTERP1)
% containing a "raised cosine" soft threshold function:
%
%   Y = VALUES(1) + (VALUES(2)-VALUES(1)) *
%       cos^2( PI/2 * (X - POSITION + WIDTH)/WIDTH )
%
% WIDTH is the width of the region over which the transition occurs
% (default = 1). POSITION is the location of the center of the
% threshold (default = 0). VALUES (default = [0,1]) specifies the
% values to the left and right of the transition.
%
% Eero Simoncelli, 7/96.

function [X, Y] = rcosFn(width,position,values)

%-----
% OPTIONAL ARGS:
if (exist('width') ~= 1)
    width = 1;
end

if (exist('position') ~= 1)
    position = 0;
end

if (exist('values') ~= 1)
    values = [0,1];
end

%-----
sz = 256; %% arbitrary!
X = pi * [-sz-1:1] / (2*sz);
Y = values(1) + (values(2)-values(1)) * cos(X).^2;

% Make sure end values are repeated, for extrapolation...
Y(1) = Y(2);
Y(sz+3) = Y(sz+2);

X = position + (2*width/pi) * (X + pi/4);

```

May 08, 97 14:51

reconLpyr.m

Page 1/1

```

% RES = reconLpyr(PYR, INDICES, LEVS, FILT2, EDGES)
%
% Reconstruct image from Laplacian pyramid, as created by buildLpyr.
%
% PYR is a vector containing the N pyramid subbands, ordered from fine
% to coarse. INDICES is an Nx2 matrix containing the sizes of
% each subband. This is compatible with the MatLab Wavelet toolbox.
%
% LEVS (optional) should be a list of levels to include, or the string
% 'all' (default). The finest scale is number 1. The lowpass band
% corresponds to lpyrHt(INDICES)+1.
%
% FILT2 (optional) can be a string naming a standard filter (see
% namedFilter), or a vector which will be used for (separable)
% convolution. Default = 'binom5'. EDGES specifies edge-handling,
% and defaults to 'reflect1' (see corrDn).
%
% Ero Simoncelli, 6/96

function res = reconLpyr(pyr, ind, levs, filt2, edges)

if nargin < 2
    error('First two arguments (PYR, INDICES) are required');
end

%%% DEFAULTS:

if (exist('levs') ~= 1)
    levs = 'all';
end

if (exist('filt2') ~= 1)
    filt2 = 'binom5';
end

if (exist('edges') ~= 1)
    edges = 'reflect1';
end
%%%-----

maxLev = 1+lpyrHt(ind);
if strcmp(levs,'all')
    levs = [1:maxLev]';
else
    if (any(levs > maxLev))
        error(sprintf('Level numbers must be in the range [1, %d].', maxLev));
    end
    levs = levs(:);
end

if isstr(filt2)
    filt2 = namedFilter(filt2);
end

filt2 = filt2(:);
res_sz = ind(1,:);

if any(levs > 1)

    int_sz = [ind(1,1), ind(2,2)];

    nres = reconLpyr( pyr(prod(res_sz)+1:size(pyr,1)), ...
        ind(2:size(ind,1),:), levs-1, filt2, edges);

    if (res_sz(1) == 1)
        res = upConv(nres, filt2', edges, [1 2], [1 1], res_sz);
    elseif (res_sz(2) == 1)
        res = upConv(nres, filt2, edges, [2 1], [1 1], res_sz);
    else
        hi = upConv(nres, filt2, edges, [2 1], [1 1], int_sz);
        res = upConv(hi, filt2', edges, [1 2], [1 1], res_sz);
    end

else

    res = zeros(res_sz);

end

if any(levs == 1)
    res = res + pyrBand(pyr,ind,1);
end

```

Aug 28, 02 21:57

reconSFpyrLevs.m

Page 1/1

```

% RESDFT = reconSFpyrLevs(PYR, INDICES, LOGRAD, XRCOS, YRCOS, ANGLE, NBANDS, LEVS, BANDS)
%
% Recursive function for reconstructing levels of a steerable pyramid
% representation. This is called by reconSFpyr, and is not usually
% called directly.
%
% Ero Simoncelli, 5/97.

function resdft = reconSFpyrLevs(pyr,pind,log_rad,Xrcos,Yrcos,angle,nbands,levs,
bands);

lo_ind = nbands+1;
dims = pind(1,:);
ctr = ceil((dims+0.5)/2);

% log_rad = log_rad + 1;
Xrcos = Xrcos - log2(2); % shift origin of lut by 1 octave.

if any(levs > 1)

    lodims = ceil((dims-0.5)/2);
    loctr = ceil((lodims+0.5)/2);
    lostart = ctr-loctr+1;
    loend = lostart+lodims-1;
    nlog_rad = log_rad(lostart(1):loend(1),lostart(2):loend(2));
    nangle = angle(lostart(1):loend(1),lostart(2):loend(2));

    if (size(pind,1) > lo_ind)
        nresdft = reconSFpyrLevs( pyr(1+sum(prod(pind(1:lo_ind-1,:))):size(pyr,1)),
        ...
            pind(lo_ind:size(pind,1),:), ...
            nlog_rad, Xrcos, Yrcos, nangle, nbands,levs-1, bands);
    else
        nresdft = fftshift(fft2(pyrBand(pyr,pind,lo_ind)));
    end

    YIrcos = sqrt(abs(1.0 - Yrcos.^2));
    lomask = pointOp(nlog_rad, YIrcos, Xrcos(1), Xrcos(2)-Xrcos(1), 0);

    resdft = zeros(dims);
    resdft(lostart(1):loend(1),lostart(2):loend(2)) = nresdft .* lomask;

else

    resdft = zeros(dims);

end

if any(levs == 1)

    lutsize = 1024;
    Xcosn = pi*[-(2*lutsize+1):(lutsize+1)]/lutsize; % [-2*pi:pi]
    order = nbands-1;
    %% divide by sqrt(sum_n=0^{N-1} cos(pi*n/N)^(2(N-1)) )
    const = (2^(2*order))*factorial(order)^2/(nbands*factorial(2*order));
    Ycosn = sqrt(const) * (cos(Xcosn)).^order;
    himask = pointOp(log_rad, Yrcos, Xrcos(1), Xrcos(2)-Xrcos(1),0);

    ind = 1;
    for b = 1:nbands
        if any(bands == b)
            anglemask = pointOp(angle,Ycosn,Xcosn(1)+pi*(b-1)/nbands,Xcosn(2)-Xcosn(1)
);
            band = reshape(pyr(ind:ind+prod(dims)-1), dims(1), dims(2));
            banddft = fftshift(fft2(band));
            resdft = resdft + (sqrt(-1))^(nbands-1) * banddft.*anglemask.*himask;
        end
        ind = ind + prod(dims);
    end
end

```

Jun 30, 97 12:55

reconSFpyr.m

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```

% RES = reconSFpyr(PYR, INDICES, LEVS, BANDS, TWIDTH)
%
% Reconstruct image from its steerable pyramid representation, in the Fourier
% domain, as created by buildSFpyr.
%
% PYR is a vector containing the N pyramid subbands, ordered from fine
% to coarse. INDICES is an Nx2 matrix containing the sizes of
% each subband. This is compatible with the MatLab Wavelet toolbox.
%
% LEVS (optional) should be a list of levels to include, or the string
% 'all' (default). 0 corresponds to the residual highpass subband.
% 1 corresponds to the finest oriented scale. The lowpass band
% corresponds to number spyrHt(INDICES)+1.
%
% BANDS (optional) should be a list of bands to include, or the string
% 'all' (default). 1 = vertical, rest proceeding anti-clockwise.
%
% TWIDTH is the width of the transition region of the radial lowpass
% function, in octaves (default = 1, which gives a raised cosine for
% the bandpass filters).
%
% Ero Simoncelli, 5/97.
function res = reconSFpyr(pyr, pind, levs, bands, twidth)
%-----
%% DEFAULTS:
if (exist('levs') ~= 1)
    levs = 'all';
end
if (exist('bands') ~= 1)
    bands = 'all';
end
if (exist('twidth') ~= 1)
    twidth = 1;
elseif (twidth <= 0)
    fprintf(1, 'Warning: TWIDTH must be positive. Setting to 1.\n');
    twidth = 1;
end
%-----
nbands = spyrNumBands(pind);
maxLev = 1+spyrHt(pind);
if strcmp(levs, 'all')
    levs = [0:maxLev]';
else
    if (any(levs > maxLev) | any(levs < 0))
        error(sprintf('Level numbers must be in the range [0, %d].', maxLev));
    end
    levs = levs(:);
end
if strcmp(bands, 'all')
    bands = [1:nbands]';
else
    if (any(bands < 1) | any(bands > nbands))
        error(sprintf('Band numbers must be in the range [1,3].', nbands));
    end
    bands = bands(:);
end
%-----
dims = pind(1,:);
ctr = ceil((dims+0.5)/2);
[xramp, yramp] = meshgrid( [1:dims(2)]-ctr(2))./(dims(2)/2), ...
    ([1:dims(1)]-ctr(1))./(dims(1)/2) );
angle = atan2(yramp, xramp);
log_rad = sqrt(xramp.^2 + yramp.^2);
log_rad(ctr(1), ctr(2)) = log_rad(ctr(1), ctr(2)-1);
log_rad = log2(log_rad);
%% Radial transition function (a raised cosine in log-frequency):
[Xrcos, Yrcos] = rcosFn(twidth, (-twidth/2), [0 1]);
Yrcos = sqrt(Yrcos);
Yrcos = sqrt(abs(1.0 - Yrcos.^2));
if (size(pind,1) == 2)
    if (any(levs==1))
        resdft = fftshift(fft2(pyrBand(pyr, pind, 2)));
    else
        resdft = zeros(pind(2,:));
    end
else
    resdft = reconSFpyrLevs(pyr(1+prod(pind(1,:)):size(pyr,1)), ...
        pind(2:size(pind,1),:), ...
        log_rad, Xrcos, Yrcos, angle, nbands, levs, bands);
end
lo0mask = pointOp(log_rad, Yrcos, Xrcos(1), Xrcos(2)-Xrcos(1), 0);
resdft = resdft .* lo0mask;
%% residual highpass subband
if any(levs == 0)
    hi0mask = pointOp(log_rad, Yrcos, Xrcos(1), Xrcos(2)-Xrcos(1), 0);
    hidft = fftshift(fft2(subMtx(pyr, pind(1,:))));
    resdft = resdft + hidft .* hi0mask;
end
res = real(ifft2(ifftshift(resdft)));

```

Dec 16, 02 17:54

reconSpyrLevs.m

Page 1/1

```

% RES = reconSpyrLevs(PYR, INDICES, LOFILTS, BFILTS, EDGES, LEVS, BANDS)
%
% Recursive function for reconstructing levels of a steerable pyramid
% representation. This is called by reconSpyr, and is not usually
% called directly.
%
% Ero Simoncelli, 6/96.
function res = reconSpyrLevs(pyr, pind, lofilt, bfilts, edges, levs, bands);
nbands = size(bfilts,2);
lo_ind = nbands+1;
res_sz = pind(1,:);
% Assume square filters:
bfiltsz = round(sqrt(size(bfilts,1)));
if any(levs > 1)
    if (size(pind,1) > lo_ind)
        nres = reconSpyrLevs( pyr(1+sum(prod(pind(1:lo_ind-1,:))):size(pyr,1)), ...
            pind(lo_ind:size(pind,1),:), ...
            lofilt, bfilts, edges, levs-1, bands);
    else
        nres = pyrBand(pyr, pind, lo_ind); % lowpass subband
    end
    res = upConv(nres, lofilt, edges, [2 2], [1 1], res_sz);
else
    res = zeros(res_sz);
end
if any(levs == 1)
    ind = 1;
    for b = 1:nbands
        if any(bands == b)
            bfiltsz = reshape(bfilts(:,b), bfiltsz, bfiltsz);
            upConv(reshape(pyr(ind:ind+prod(res_sz)-1), res_sz(1), res_sz(2)), ...
                bfilts, edges, [1 1], [1 1], res_sz, res);
            ind = ind + prod(res_sz);
        end
    end
end
end

```

Dec 16, 02 17:54

reconSpyr.m

Page 1/1

```

% RES = reconSpyr(PYR, INDICES, FILTFILE, EDGES, LEVS, BANDS)
%
% Reconstruct image from its steerable pyramid representation, as created
% by buildSpyr.
%
% PYR is a vector containing the N pyramid subbands, ordered from fine
% to coarse. INDICES is an Nx2 matrix containing the sizes of
% each subband. This is compatible with the MatLab Wavelet toolbox.
%
% FILTFILE (optional) should be a string referring to an m-file that returns
% the rfilters. examples: sp0Filters, sp1Filters, sp3Filters
% (default = 'sp1Filters').
% EDGES specifies edge-handling, and defaults to 'reflect1' (see
% corrDn).
%
% LEVS (optional) should be a list of levels to include, or the string
% 'all' (default). 0 corresponds to the residual highpass subband.
% 1 corresponds to the finest oriented scale. The lowpass band
% corresponds to number spyrHt(INDICES)+1.
%
% BANDS (optional) should be a list of bands to include, or the string
% 'all' (default). 1 = vertical, rest proceeding anti-clockwise.
%
% Ero Simoncelli, 6/96.

function res = reconSpyr(pyr, pind, filtfile, edges, levs, bands)

%%-----
%% DEFAULTS:

if (exist('filtfile') ~= 1)
    filtfile = 'sp1Filters';
end

if (exist('edges') ~= 1)
    edges = 'reflect1';
end

if (exist('levs') ~= 1)
    levs = 'all';
end

if (exist('bands') ~= 1)
    bands = 'all';
end

%%-----

if (isstr(filtfile) & (exist(filtfile) == 2))
    [lo0filt,hi0filt,lofilt,bfilters,steermx,harmonics] = eval(filtfile);
    nbands = spyrNumBands(pind);
    if (nbands > 0) & (size(bfilters,2) ~= nbands)
        error('Number of pyramid bands is inconsistent with filter file');
    end
else
    error('filtfile argument must be the name of an M-file containing SPYR filters
    .');
end

maxLev = 1+spyrHt(pind);
if strcmp(levs,'all')
    levs = [0:maxLev];
else
    if (any(levs > maxLev) | any(levs < 0))
        error(sprintf('Level numbers must be in the range [0, %d].', maxLev));
    end
    levs = levs(:);
end

if strcmp(bands,'all')
    bands = [1:nbands];
else
    if (any(bands < 1) | any(bands > nbands))
        error(sprintf('Band numbers must be in the range [1,3].', nbands));
    end
    bands = bands(:);
end

if (spyrHt(pind) == 0)
    if (any(levs==1))
        res1 = pyrBand(pyr,pind,2);
    else
        res1 = zeros(pind(2,:));
    end
else
    res1 = reconSpyrLevs(pyr(1+prod(pind(1,:)):size(pyr,1)), ...
        pind(2:size(pind,1),:), ...
        lofilt, bfilters, edges, levs, bands);
end

res = upConv(res1, lo0filt, edges);

%% residual highpass subband
if any(levs == 0)
    upConv( subMtx(pyr, pind(1,:), hi0filt, edges, [1 1], [1 1], size(res), res)
;
end

```

May 08, 97 14:51

reconWpyr.m

Page 1/2

```

% RES = reconWpyr(PYR, INDICES, FILT, EDGES, LEVS, BANDS)
%
% Reconstruct image from its separable orthonormal QMF/wavelet pyramid
% representation, as created by buildWpyr.
%
% PYR is a vector containing the N pyramid subbands, ordered from fine
% to coarse. INDICES is an Nx2 matrix containing the sizes of
% each subband. This is compatible with the MatLab Wavelet toolbox.
%
% FILT (optional) can be a string naming a standard filter (see
% namedFilter), or a vector which will be used for (separable)
% convolution. Default = 'qmf9'. EDGES specifies edge-handling,
% and defaults to 'reflect1' (see corrDn).
%
% LEVS (optional) should be a vector of levels to include, or the string
% 'all' (default). 1 corresponds to the finest scale. The lowpass band
% corresponds to wpyrHt(INDICES)+1.
%
% BANDS (optional) should be a vector of bands to include, or the string
% 'all' (default). 1=horizontal, 2=vertical, 3=diagonal. This is only used
% for pyramids of 2D images.
%
% Ero Simoncelli, 6/96.

function res = reconWpyr(pyr, ind, filt, edges, levs, bands)

if (margin < 2)
    error('First two arguments (PYR INDICES) are required');
end

%%-----
%% OPTIONAL ARGS:

if (exist('filt') ~= 1)
    filt = 'qmf9';
end

if (exist('edges') ~= 1)
    edges = 'reflect1';
end

if (exist('levs') ~= 1)
    levs = 'all';
end

if (exist('bands') ~= 1)
    bands = 'all';
end

%%-----

maxLev = 1+wpyrHt(ind);
if strcmp(levs,'all')
    levs = [1:maxLev];
else
    if (any(levs > maxLev))
        error(sprintf('Level numbers must be in the range [1, %d].', maxLev));
    end
    levs = levs(:);
end

if strcmp(bands,'all')
    bands = [1:3];
else
    if (any(bands < 1) | any(bands > 3))
        error('Band numbers must be in the range [1,3].');
    end
    bands = bands(:);
end

if isstr(filt)
    filt = namedFilter(filt);
end

filt = filt(:);
hfilt = modulateFlip(filt);

%% For odd-length filters, stagger the sampling lattices:
if (mod(size(filt,1),2) == 0)
    stag = 2;
else
    stag = 1;
end

%% Compute size of result image: assumes critical sampling (boundaries correct)
res_sz = ind(1,:);
if (res_sz(1) == 1)
    loind = 2;
    res_sz(2) = sum(ind(:,2));
elseif (res_sz(2) == 1)
    loind = 2;
    res_sz(1) = sum(ind(:,1));
else
    loind = 4;
    res_sz = ind(1,:) + ind(2,:); %horizontal + vertical bands.
    hres_sz = [ind(1,1), res_sz(2)];
    lres_sz = [ind(2,1), res_sz(2)];
end

%% First, recursively collapse coarser scales:
if any(levs > 1)

    if (size(ind,1) > loind)
        nres = reconWpyr( pyr(1+sum(prod(ind(1:loind-1,:)))size(pyr,1)), ...
            ind(loind:size(ind,1),:), filt, edges, levs-1, bands);
    else
        nres = pyrBand(pyr, ind, loind); % lowpass subband
    end

    if (res_sz(1) == 1)
        res = upConv(nres, filt', edges, [1 2], [1 stag], res_sz);
    elseif (res_sz(2) == 1)
        res = upConv(nres, filt, edges, [2 1], [stag 1], res_sz);
    else
        ires = upConv(nres, filt', edges, [1 2], [1 stag], lres_sz);
        res = upConv(ires, filt, edges, [2 1], [stag 1], res_sz);
    end

else
    res = zeros(res_sz);
end
end

```

May 08, 97 14:51

reconWpyr.m

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```

%% Add in reconstructed bands from this level:
if any(levs == 1)
    if (res_sz(1) == 1)
        upConv(pyrBand(pyr,ind,1), hfilt', edges, [1 2], [1 2], res_sz, res);
    elseif (res_sz(2) == 1)
        upConv(pyrBand(pyr,ind,1), hfilt, edges, [2 1], [2 1], res_sz, res);
    else
        if any(bands == 1) % horizontal
            ires = upConv(pyrBand(pyr,ind,1),filt',edges,[1 2],[1 stag],hres_sz);
            upConv(ires,hfilt,edges,[2 1],[2 1],res_sz,res); %destructively modify re
        s
        end
        if any(bands == 2) % vertical
            ires = upConv(pyrBand(pyr,ind,2),hfilt',edges,[1 2],[1 2],lres_sz);
            upConv(ires,filt,edges,[2 1],[stag 1],res_sz,res); %destructively modify
        res
        end
        if any(bands == 3) % diagonal
            ires = upConv(pyrBand(pyr,ind,3),hfilt',edges,[1 2],[1 2],hres_sz);
            upConv(ires,hfilt,edges,[2 1],[2 1],res_sz,res); %destructively modify re
        s
        end
    end
end
end

```

May 30, 03 9:15

setPyrBand.m

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```

% NEWPYR = setPyrBand(PYR, INDICES, BAND, BAND_NUM)
%
% Insert an image (BAND) into a pyramid (gaussian, laplacian, QMF/wavelet,
% or steerable). Subbands are numbered consecutively, from finest
% (highest spatial frequency) to coarsest (lowest spatial frequency).
%
% Eroo Simoncelli, 1/03.
function pyr = pyrBand(pyr, pind, band, bandNum)
%% Check: PIND a valid index matrix?
if (~(ndims(pind) == 2) | ~(size(pind,2) == 2) | ~all(pind==round(pind))) )
    pind
    error('pyrTools:badArg',...
        'PIND argument is not an Nbands X 2 matrix of integers');
end
%% Check: PIND consistent with size of PYR?
if ( length(pyr) ~= sum(prod(pind,2)) )
    error('pyrTools:badPyr',...
        'Pyramid data vector length is inconsistent with index matrix PIND');
end
%% Check: size of BAND consistent with desired BANDNUM?
if (~all(size(band) == pind(bandNum,:)))
    size(band)
    pind(bandNum,:)
    error('pyrTools:badArg',...
        'size of BAND to be inserted is inconsistent with BAND_NUM');
end
pyr(pyrBandIndices(pind,bandNum)) = vectify(band);

```

Aug 14, 97 15:21

shift.m

Page 1/1

```

% [RES] = shift(MTX, OFFSET)
%
% Circular shift 2D matrix samples by OFFSET (a [Y,X] 2-vector),
% such that RES(POS) = MTX(POS-OFFSET).
function res = shift(mtx, offset)

dims = size(mtx);

offset = mod(-offset,dims);

res = [ mtx(offset(1)+1:dims(1), offset(2)+1:dims(2)), ...
        mtx(offset(1)+1:dims(1), 1:offset(2)); ...
        mtx(1:offset(1), offset(2)+1:dims(2)), ...
        mtx(1:offset(1), 1:offset(2)) ];

```

Apr 16, 98 18:27

showIm.m

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```

% RANGE = showIm (MATRIX, RANGE, ZOOM, LABEL, NSHADES )
%
% Display a MatLab MATRIX as a grayscale image in the current figure,
% inside the current axes. If MATRIX is complex, the real and imaginary
% parts are shown side-by-side, with the same grayscale mapping.
%
% If MATRIX is a string, it should be the name of a variable bound to a
% MATRIX in the base (global) environment. This matrix is displayed as an
% image, with the title set to the string.
%
% RANGE (optional) is a 2-vector specifying the values that map to
% black and white, respectively. Passing a value of 'auto' (default)
% sets RANGE=[min,max] (as in MatLab's imagesc). 'auto2' sets
% RANGE=[mean-2*stdev, mean+2*stdev]. 'auto3' sets
% RANGE=[p1-(p2-p1)/8, p2+(p2-p1)/8], where p1 is the 10th percentile
% value of the sorted MATRIX samples, and p2 is the 90th percentile
% value.
%
% ZOOM specifies the number of matrix samples per screen pixel. It
% will be rounded to an integer, or 1 divided by an integer. A value
% of 'same' or 'auto' (default) causes the zoom value to be chosen
% automatically to fit the image into the current axes. A value of
% 'full' fills the axis region (leaving no room for labels). See
% pixelAxes.m.
%
% If LABEL (optional, default = 1, unless zoom='full') is non-zero, the range
% of values that are mapped into the gray colormap and the dimensions
% (size) of the matrix and zoom factor are printed below the image. If label
% is a string, it is used as a title.
%
% NSHADES (optional) specifies the number of gray shades, and defaults
% to the size of the current colormap.
%
% Eero Simoncelli, 6/96.
%
% TODO: should use "newplot"
function range = showIm( im, range, zoom, label, nshades );
%-----
%% OPTIONAL ARGS:

if (nargin < 1)
    error('Requires at least one input argument.');
```

```

end

MLv = version;

if isstr(im)
    if (strcmp(MLv(1),'4'))
        error('Cannot pass string arg for MATRIX in MatLab version 4.x');
```

```

    end
    label = im;
    im = evalin('base',im);
end

if (exist('range') ~= 1)
    range = 'auto1';
end

if (exist('nshades') ~= 1)
    nshades = size(colormap,1);
end
nshades = max( nshades, 2 );

if (exist('zoom') ~= 1)
    zoom = 'auto';
end

if (exist('label') ~= 1)
    if strcmp(zoom,'full')
        label = 0; % no labeling
    else
        label = 1; % just print grayrange & dims
    end
end

%-----

%% Automatic range calculation:
if (strcmp(range,'auto1') | strcmp(range,'auto'))
    if isreal(im)
        [mn,mx] = range2(im);
    else
        [mn1,mx1] = range2(real(im));
        [mn2,mx2] = range2(imag(im));
        mn = min(mn1,mn2);
        mx = max(mx1,mx2);
    end
    if any(size(im)==1)
        pad = (mx-mn)/12; % MAGIC NUMBER: graph padding
        range = [mn-pad, mx+pad];
    else
        range = [mn,mx];
    end
elseif strcmp(range,'auto2')
    if isreal(im)
        stdev = sqrt(var2(im));
        av = mean2(im);
    else
        stdev = sqrt((var2(real(im)) + var2(imag(im)))/2);
        av = (mean2(real(im)) + mean2(imag(im)))/2;
    end
    range = [av-2*stdev,av+2*stdev]; % MAGIC NUMBER: 2 stdevs
elseif strcmp(range,'auto3')
    percentile = 0.1; % MAGIC NUMBER: 0<p<0.5
    [N,X] = histo(im);
    binsz = X(2)-X(1);
    N = N+le-10; % Ensure cumsum will be monotonic for call to interp1
    cumN = [0, cumsum(N)]/sum(N);
    cumX = [X(1)-binsz, X] + (binsz/2);
    ctrRange = interp1(cumN,cumX, [percentile, 1-percentile]);
    range = mean(ctrRange) + (ctrRange-mean(ctrRange))/(1-2*percentile);
elseif isstr(range)
    error(sprintf('Bad RANGE argument: %s',range))
end

if ((range(2) - range(1)) <= eps)
    range(1) = range(1) - 0.5;
    range(2) = range(2) + 0.5;

```

Apr 16, 98 18:27

showIm.m

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```

end

if isreal(im)
    factor=1;
else
    factor = 1+sqrt(-1);
end

xlabel_offset = 0; % default value

if (~any(size(im))==1)
    %% Matlab's "image" rounds when mapping to the colormap, so we compute
    %% (im-r1)*(nshades-1)/(r2-r1) + 1.5
    mult = ((nshades-1) / (range(2)-range(1)));
    d_im = (mult * im) + factor*(1.5 - range(1)*mult);
end

if isreal(im)
    if (any(size(im))==1)
        hh = plot(im);
        axis([1, prod(size(im)), range]);
    else
        hh = image(d_im);
        axis('off');
        zoom = pixelAxes(size(d_im),zoom);
    end
else
    if (any(size(im))==1)
        subplot(2,1,1);
        hh = plot(real(im));
        axis([1, prod(size(im)), range]);
        subplot(2,1,2);
        hh = plot(imag(im));
        axis([1, prod(size(im)), range]);
    else
        subplot(1,2,1);
        hh = image(real(d_im));
        axis('off'); zoom = pixelAxes(size(d_im),zoom);
        ax = gca; orig_units = get(ax,'Units');
        set(ax,'Units','points');
        pos1 = get(ax,'Position');
        set(ax,'Units',orig_units);
        subplot(1,2,2);
        hh = image(imag(d_im));
        axis('off'); zoom = pixelAxes(size(d_im),zoom);
        ax = gca; orig_units = get(ax,'Units');
        set(ax,'Units','points');
        pos2 = get(ax,'Position');
        set(ax,'Units',orig_units);
        xlabel_offset = (pos1(1)-pos2(1))/2;
    end
end

if ~any(size(im))==1
    colormap(gray(nshades));
end

if ((label ~= 0))
    if isstr(label)
        title(label);
        h = get(gca,'Title');
        orig_units = get(h,'Units');
        set(h,'Units','points');
        pos = get(h,'Position');
        pos(1:2) = pos(1:2) + [xlabel_offset, -3]; % MAGIC NUMBER: y pixel offset
        set(h,'Position',pos);
        set(h,'Units',orig_units);
    end

    if (~any(size(im))==1)
        if (zoom > 1)
            zformat = sprintf('%d',round(zoom));
        else
            zformat = sprintf('/ %d',round(1/zoom));
        end
        if isreal(im)
            format=[ '%.3g, %.3g' \n Dims: [%d, %d] ', zformat];
        else
            format=[ '%.3g, %.3g' ---- Dims: [%d, %d]', zformat];
        end
        xlabel(sprintf(format, range(1), range(2), size(im,1), size(im,2)));
        h = get(gca,'Xlabel');
        set(h,'FontSize', 9); % MAGIC NUMBER: font size!!!

        orig_units = get(h,'Units');
        set(h,'Units','points');
        pos = get(h,'Position');
        pos(1:2) = pos(1:2) + [xlabel_offset, 10]; % MAGIC NUMBER: y offset in points
        set(h,'Position',pos);
        set(h,'Units',orig_units);

        set(h,'Visible','on'); % axis('image') turned the xlabel off.
    end
end
return;

```

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May 28, 97 19:11

showLpyr.m

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```

% RANGE = showLpyr (PYR, INDICES, RANGE, GAP, LEVEL_SCALE_FACTOR)
%
% Display a Laplacian (or Gaussian) pyramid, specified by PYR and
% INDICES (see buildLpyr), in the current figure.
%
% RANGE is a 2-vector specifying the values that map to black and
% white, respectively. These values are scaled by
% LEVEL_SCALE_FACTOR^(lev-1) for bands at each level. Passing a value
% of 'auto1' sets RANGE to the min and max values of MATRIX. 'auto2'
% sets RANGE to 3 standard deviations below and above 0.0. In both of
% these cases, the lowpass band is independently scaled. A value of
% 'indep1' sets the range of each subband independently, as in a call
% to showIm(subband,'auto1'). Similarly, 'indep2' causes each subband
% to be scaled independently as if by showIm(subband,'indep2').
% The default value for RANGE is 'auto1' for 1D images, and 'auto2' for
% 2D images.
%
% GAP (optional, default=1) specifies the gap in pixels to leave
% between subbands (2D images only).
%
% LEVEL_SCALE_FACTOR indicates the relative scaling between pyramid
% levels. This should be set to the sum of the kernel taps of the
% lowpass filter used to construct the pyramid (default assumes
% L2-normalized filters, using a value of 2 for 2D images, sqrt(2) for
% 1D images).
%
% Ero Simoncelli, 2/97.

function [range] = showLpyr(pyr, pind, range, gap, scale);

% Determine 1D or 2D pyramid:
if ((pind(1,1) == 1) | (pind(1,2) == 1))
    oned = 1;
else
    oned = 0;
end

%-----
%% OPTIONAL ARGS:
if (exist('range') ~= 1)
    if (oned==1)
        range = 'auto1';
    else
        range = 'auto2';
    end
end

if (exist('gap') ~= 1)
    gap = 1;
end

if (exist('scale') ~= 1)
    if (oned == 1)
        scale = sqrt(2);
    else
        scale = 2;
    end
end

%-----
nind = size(pind,1);

%% Auto range calculations:
if strcmp(range,'auto1')
    range = zeros(nind,1);
    mn = 0.0; mx = 0.0;
    for bnum = 1:(nind-1)
        band = pyrBand(pyr,pind,bnum)/(scale^(bnum-1));
        range(bnum) = scale^(bnum-1);
        [bmn,bmx] = range2(band);
        mn = min(mn, bmn); mx = max(mx, bmx);
    end
    if (oned == 1)
        pad = (mx-mn)/12; % *** MAGIC NUMBER!!
        mn = mn-pad; mx = mx+pad;
    end
    range = range * [mn mx]; % outer product
    band = pyrLow(pyr,pind);
    [mn,mx] = range2(band);
    if (oned == 1)
        pad = (mx-mn)/12; % *** MAGIC NUMBER!!
        mn = mn-pad; mx = mx+pad;
    end
    range(nind,:) = [mn, mx];
elseif strcmp(range,'indep1')
    range = zeros(nind,2);
    for bnum = 1:nind
        band = pyrBand(pyr,pind,bnum);
        [mn,mx] = range2(band);
        if (oned == 1)
            pad = (mx-mn)/12; % *** MAGIC NUMBER!!
            mn = mn-pad; mx = mx+pad;
        end
        range(bnum,:) = [mn mx];
    end
elseif strcmp(range,'auto2')
    range = zeros(nind,1);
    sqsum = 0; numpixels = 0;
    for bnum = 1:(nind-1)
        band = pyrBand(pyr,pind,bnum)/(scale^(bnum-1));
        sqsum = sqsum + sum(sum(band.^2));
        numpixels = numpixels + prod(size(band));
        range(bnum) = scale^(bnum-1);
    end
    stdev = sqrt(sqsum/(numpixels-1));
    range = range * [-3*stdev 3*stdev]; % outer product
    band = pyrLow(pyr,pind);
    av = mean2(band); stdev = sqrt(var2(band));
    range(nind,:) = [av-2*stdev,av+2*stdev];
elseif strcmp(range,'indep2')
    range = zeros(nind,2);
    for bnum = 1:(nind-1)
        band = pyrBand(pyr,pind,bnum);
        stdev = sqrt(var2(band));
        range(bnum,:) = [-3*stdev 3*stdev];
    end
    band = pyrLow(pyr,pind);
    av = mean2(band); stdev = sqrt(var2(band));
    range(nind,:) = [av-2*stdev,av+2*stdev];
end

```

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May 28, 97 19:11

showLpyr.m

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```

elseif isstr(range)
    error(sprintf('Bad RANGE argument: %s',range))

elseif ((size(range,1) == 1) & (size(range,2) == 2))
    scales = scale.^[0:nind-1];
    range = scales(:) * range;           % outer product
    band = pyrLow(pyr,pind);
    range(nind,:) = range(nind,:) + mean2(band) - mean(range(nind,:));

end

%% Clear Figure
clf;

if (oned == 1)
    %%%% 1D signal:
    for bnum=1:nind
        band = pyrBand(pyr,pind,bnum);
        subplot(nind,1,nind-bnum+1);
        plot(band);
        axis([1, prod(size(band)), range(bnum,:)]);
    end
else
    %%%% 2D signal:
    colormap(gray);
    cmap = get(gcf,'Colormap');
    nshades = size(cmap,1);

    % Find background color index:
    clr = get(gcf,'Color');
    bg = 1;
    dist = norm(cmap(bg,:)-clr);
    for n = 1:nshades
        ndist = norm(cmap(n,:)-clr);
        if (ndist < dist)
            dist = ndist;
            bg = n;
        end
    end

    %% Compute positions of subbands:
    llpos = ones(nind,2);
    dir = [-1 -1];
    ctr = [pind(1,1)+1+gap 1];
    sz = [0 0];
    for bnum = 1:nind
        prevsz = sz;
        sz = pind(bnum,:);

        % Determine center position of new band:
        ctr = ctr + gap*dir/2 + dir.* floor((prevsz+(dir>0))/2);
        dir = dir * [0 -1; 1 0]; % cw rotation
        ctr = ctr + gap*dir/2 + dir.* floor((sz+(dir<0))/2);
        llpos(bnum,:) = ctr - floor(sz./2);
    end

    %% Make position list positive, and allocate appropriate image:
    llpos = llpos - ones(nind,1)*min(llpos) + 1;
    urpos = llpos + pind - 1;
    d_im = bg + zeros(max(urpos));

    %% Paste bands into image, (im-r1)*(nshades-1)/(r2-r1) + 1.5
    for bnum=1:nind
        mult = (nshades-1) / (range(bnum,2)-range(bnum,1));
        d_im(llpos(bnum,1):urpos(bnum,1), llpos(bnum,2):urpos(bnum,2)) = ...
            mult*pyrBand(pyr,pind,bnum) + (1.5-mult*range(bnum,1));
    end

    hh = image(d_im);
    axis('off');
    pixelAxes(size(d_im),'full');
    set(hh,'UserData',range);

end

```

May 22, 97 15:37

showSpyr.m

Page 1/2

```

% RANGE = showSpyr (PYR, INDICES, RANGE, GAP, LEVEL_SCALE_FACTOR)
%
% Display a steerable pyramid, specified by PYR and INDICES
% (see buildSpyr), in the current figure. The highpass band is not shown.
%
% RANGE is a 2-vector specifying the values that map to black and
% white, respectively. These values are scaled by
% LEVEL_SCALE_FACTOR^(lev-1) for bands at each level. Passing a value
% of 'auto1' sets RANGE to the min and max values of MATRIX. 'auto2'
% sets RANGE to 3 standard deviations below and above 0.0. In both of
% these cases, the lowpass band is independently scaled. A value of
% 'indep1' sets the range of each subband independently, as in a call
% to showIm(subband,'auto1'). Similarly, 'indep2' causes each subband
% to be scaled independently as if by showIm(subband,'indep2').
% The default value for RANGE is 'auto2'.
%
% GAP (optional, default=1) specifies the gap in pixels to leave
% between subbands.
%
% LEVEL_SCALE_FACTOR indicates the relative scaling between pyramid
% levels. This should be set to the sum of the kernel taps of the
% lowpass filter used to construct the pyramid (default is 2, which is
% correct for L2-normalized filters.
%
% Ero Simoncelli, 2/97.

function [range] = showSpyr(pyr, pind, range, gap, scale);

nbands = spyrNumBands(pind);

%-----
%% OPTIONAL ARGS:

if (exist('range') ~= 1)
    range = 'auto2';
end

if (exist('gap') ~= 1)
    gap = 1;
end

if (exist('scale') ~= 1)
    scale = 2;
end

%-----

ht = spyrHt(pind);
nind = size(pind,1);

%% Auto range calculations:
if strcmp(range,'auto1')
    range = ones(nind,1);
    band = spyrHigh(pyr,pind);
    [mn,mx] = range2(band);
    for lnum = 1:nbands
        for bnum = 1:nbands
            band = spyrBand(pyr,pind,lnum,bnum)/(scale^(lnum-1));
            range((lnum-1)*nbands+bnum+1) = scale^(lnum-1);
            [bmn,bmx] = range2(band);
            mn = min(mn, bmn);
            mx = max(mx, bmx);
        end
    end
    range = range * [mn mx];           % outer product
    band = pyrLow(pyr,pind);
    [mn,mx] = range2(band);
    range(nind,:) = [mn, mx];

elseif strcmp(range,'indep1')
    range = zeros(nind,2);
    for bnum = 1:nind
        band = pyrBand(pyr,pind,bnum);
        [mn,mx] = range2(band);
        range(bnum,:) = [mn mx];
    end

elseif strcmp(range,'auto2')
    range = ones(nind,1);
    band = spyrHigh(pyr,pind);
    sqsum = sum(sum(band.^2)); numpixels = prod(size(band));
    for lnum = 1:ht
        for bnum = 1:nbands
            band = spyrBand(pyr,pind,lnum,bnum)/(scale^(lnum-1));
            sqsum = sqsum + sum(sum(band.^2));
            numpixels = numpixels + prod(size(band));
            range((lnum-1)*nbands+bnum+1) = scale^(lnum-1);
        end
    end
    stdev = sqrt(sqsum/(numpixels-1));
    range = range * [-3*stdev 3*stdev]; % outer product
    band = pyrLow(pyr,pind);
    av = mean2(band); stdev = sqrt(var2(band));
    range(nind,:) = [av-2*stdev,av+2*stdev];

elseif strcmp(range,'indep2')
    range = zeros(nind,2);
    for bnum = 1:(nind-1)
        band = pyrBand(pyr,pind,bnum);
        stdev = sqrt(var2(band));
        range(bnum,:) = [-3*stdev 3*stdev];
    end
    band = pyrLow(pyr,pind);
    av = mean2(band); stdev = sqrt(var2(band));
    range(nind,:) = [av-2*stdev,av+2*stdev];

elseif isstr(range)
    error(sprintf('Bad RANGE argument: %s',range))

elseif ((size(range,1) == 1) & (size(range,2) == 2))
    scales = scale.^[0:(ht-1)];
    scales = ones(nbands,1) * scales; %outer product
    scales = [1; scales(:); scale*ht]; %tack on highpass and lowpass
    range = scales * range;           % outer product
    band = pyrLow(pyr,pind);
    range(nind,:) = range(nind,:) + mean2(band) - mean(range(nind,:));

end

% CLEAR FIGURE:
clf;

colormap(gray);
cmap = get(gcf,'Colormap');

```

May 22, 97 15:37

showSpyr.m

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```

nshades = size(cmap,1);

% Find background color index:
clr = get(gcf,'Color');
bg = 1;
dist = norm(cmap(bg,:)-clr);
for n = 1:nshades
    ndist = norm(cmap(n,:)-clr);
    if (ndist < dist)
        dist = ndist;
        bg = n;
    end
end

%% Compute positions of subbands:
llpos = ones(nind,2);

if (nbands == 2)
    ncols = 1; nrows = 2;
else
    ncols = ceil((nbands+1)/2); nrows = ceil(nbands/2);
end
relpos = [ (1-nrows):0, zeros(1,(ncols-1)); ...
           zeros(1,nrows), -1:-1:(1-ncols) ]';
if (nbands > 1)
    mvpos = [-1 -1];
else
    mvpos = [0 -1];
end
basepos = [0 0];

for lnum = 1:ht
    ind1 = (lnum-1)*nbands + 2;
    sz = pind(ind1,:)+gap;
    basepos = basepos + mvpos .* sz;
    if (nbands < 5) % to align edges...
        sz = sz + gap*(ht-lnum+1);
    end
    llpos(ind1:ind1+nbands-1,:) = relpos * diag(sz) + ones(nbands,1)*basepos;
end

% lowpass band
sz = pind(nind-1,:)+gap;
basepos = basepos + mvpos .* sz;
llpos(nind,:) = basepos;

%% Make position list positive, and allocate appropriate image:
llpos = llpos - ones(nind,1)*min(llpos) + 1;
llpos(1,:) = [1 1];
urpos = llpos + pind - 1;
d_im = bg + zeros(max(urpos));

%% Paste bands into image, (im-r1)*(nshades-1)/(r2-r1) + 1.5
for bnum=2:nind
    mult = (nshades-1) / (range(bnum,2)-range(bnum,1));
    d_im(llpos(bnum,1):urpos(bnum,1), llpos(bnum,2):urpos(bnum,2)) = ...
        mult*pyrBand(pyr,pind,bnum) + (1.5-mult*range(bnum,1));
end

hh = image(d_im);
axis('off');
pixelAxes(size(d_im),'full');
set(hh,'UserData',range);

```

Apr 26, 97 12:50

showWpyr.m

Page 1/2

```

% RANGE = showWpyr (PYR, INDICES, RANGE, GAP, LEVEL_SCALE_FACTOR)
%
% Display a separable QMF/wavelet pyramid, specified by PYR and INDICES
% (see buildWpyr), in the current figure.
%
% RANGE is a 2-vector specifying the values that map to black and
% white, respectively. These values are scaled by
% LEVEL_SCALE_FACTOR^(lev-1) for bands at each level. Passing a value
% of 'auto1' sets RANGE to the min and max values of MATRIX. 'auto2'
% sets RANGE to 3 standard deviations below and above 0.0. In both of
% these cases, the lowpass band is independently scaled. A value of
% 'indep1' sets the range of each subband independently, as in a call
% to showIm(subband,'auto1'). Similarly, 'indep2' causes each subband
% to be scaled independently as if by showIm(subband,'indep2').
% The default value for RANGE is 'auto1' for 1D images, and 'auto2' for
% 2D images.
%
% GAP (optional, default=1) specifies the gap in pixels to leave
% between subbands (2D images only).
%
% LEVEL_SCALE_FACTOR indicates the relative scaling between pyramid
% levels. This should be set to the sum of the kernel taps of the
% lowpass filter used to construct the pyramid (default assumes
% L2-normalized filters, using a value of 2 for 2D images, sqrt(2) for
% 1D images).
%
% Ero Simoncelli, 2/97.

function [range] = showWpyr(pyr, pind, range, gap, scale);

% Determine 1D or 2D pyramid:
if ((pind(1,1) == 1) | (pind(1,2) == 1))
    nbands = 1;
else
    nbands = 3;
end

%-----
%% OPTIONAL ARGS:
if (exist('range') ~= 1)
    if (nbands==1)
        range = 'auto1';
    else
        range = 'auto2';
    end
end

if (exist('gap') ~= 1)
    gap = 1;
end

if (exist('scale') ~= 1)
    if (nbands == 1)
        scale = sqrt(2);
    else
        scale = 2;
    end
end

%-----
ht = wpyrHt(pind);
nind = size(pind,1);

%% Auto range calculations:
if strcmp(range,'auto1')
    range = zeros(nind,1);
    mn = 0.0; mx = 0.0;
    for lnum = 1:ht
        for bnum = 1:nbands
            band = wpyrBand(pyr,pind,lnum,bnum)/(scale^(lnum-1));
            range((lnum-1)*nbands+bnum) = scale^(lnum-1);
            [bmn,bmx] = range2(band);
            mn = min(mn, bmn); mx = max(mx, bmx);
        end
    end
    if (nbands == 1)
        pad = (mx-mn)/12; % *** MAGIC NUMBER!!
        mn = mn-pad; mx = mx+pad;
    end
    range = range * [mn mx]; % outer product
    band = pyrLow(pyr,pind);
    [mn,mx] = range2(band);
    if (nbands == 1)
        pad = (mx-mn)/12; % *** MAGIC NUMBER!!
        mn = mn-pad; mx = mx+pad;
    end
    range(nind,:) = [mn, mx];
elseif strcmp(range,'indep1')
    range = zeros(nind,2);
    for bnum = 1:nind
        band = pyrBand(pyr,pind,bnum);
        [mn,mx] = range2(band);
        if (nbands == 1)
            pad = (mx-mn)/12; % *** MAGIC NUMBER!!
            mn = mn-pad; mx = mx+pad;
        end
        range(bnum,:) = [mn mx];
    end
elseif strcmp(range,'auto2')
    range = zeros(nind,1);
    sqsum = 0; numpixels = 0;
    for lnum = 1:ht
        for bnum = 1:nbands
            band = wpyrBand(pyr,pind,lnum,bnum)/(scale^(lnum-1));
            sqsum = sqsum + sum(sum(band.^2));
            numpixels = numpixels + prod(size(band));
            range((lnum-1)*nbands+bnum) = scale^(lnum-1);
        end
    end
    stdev = sqrt(sqsum/(numpixels-1));
    range = range * [-3*stdev 3*stdev]; % outer product
    band = pyrLow(pyr,pind);
    av = mean2(band); stdev = sqrt(var2(band));
    range(nind,:) = [av-2*stdev,av+2*stdev];
elseif strcmp(range,'indep2')
    range = zeros(nind,2);
    for bnum = 1:(nind-1)
        band = pyrBand(pyr,pind,bnum);
        stdev = sqrt(var2(band));

```

Apr 26, 97 12:50

showWpyr.m

Page 2/2

```

range(bnum,:) = [ -3*stdev 3*stdev ];
end
band = pyrLow(pyr,pind);
av = mean2(band); stdev = sqrt(var2(band));
range(nind,:) = [av-2*stdev,av+2*stdev];

elseif isstr(range)
error(sprintf('Bad RANGE argument: %s',range))

elseif ((size(range,1) == 1) & (size(range,2) == 2))
scales = scale.^[0:ht];
if (nbands ~= 1)
scales = [scales; scales; scales];
end
range = scales(:) * range; % outer product
band = pyrLow(pyr,pind);
range(nind,:) = range(nind,:) + mean2(band) - mean(range(nind,:));

end

% CLEAR FIGURE:
clf;

if (nbands == 1)

% 1D signal:
for bnum=1:nind
band = pyrBand(pyr,pind,bnum);
subplot(nind,1,nind-bnum+1);
plot(band);
axis([1, prod(size(band)), range(bnum,:)]);
end

else

% 2D signal:
colormap(gray);
cmap = get(gcf,'Colormap');
nshades = size(cmap,1);

% Find background color index:
clr = get(gcf,'Color');
bg = 1;
dist = norm(cmap(bg,:)-clr);
for n = 1:nshades
ndist = norm(cmap(n,:)-clr);
if (ndist < dist)
dist = ndist;
bg = n;
end
end

% Compute positions of subbands:
llpos = ones(nind,2);
for lnum = 1:ht
indl = nbands*(lnum-1) + 1;
xpos = pind(indl,2) + 1 + gap*(ht-lnum+1);
ypos = pind(indl+1,1) + 1 + gap*(ht-lnum+1);
llpos(indl:indl+2,:) = [ypos 1; 1 xpos; ypos xpos];
end
llpos(nind,:) = [1 1]; %lowpass

% Make position list positive, and allocate appropriate image:
llpos = llpos - ones(nind,1)*min(llpos) + 1;
urpos = llpos + pind - 1;
d_im = bg + zeros(max(urpos));

% Paste bands into image, (im-r1)*(nshades-1)/(r2-r1) + 1.5
for bnum=1:nind
mult = (nshades-1) / (range(bnum,2)-range(bnum,1));
d_im(llpos(bnum,1):urpos(bnum,1), llpos(bnum,2):urpos(bnum,2)) = ...
mult*pyrBand(pyr,pind,bnum) + (1.5-mult*range(bnum,1));
end

hh = image(d_im);
axis('off');
pixelAxes(size(d_im),'full');
set(hh,'UserData',range);

end

```

Aug 21, 97 13:56

skew2.m

Page 1/1

```

% S = SKEW2(MTX,MEAN,VAR)
%
% Sample skew (third moment divided by variance^3/2) of a matrix.
% MEAN (optional) and VAR (optional) make the computation faster.

function res = skew2(mtx, mn, v)

if (exist('mn') ~= 1)
mn = mean2(mtx);
end

if (exist('v') ~= 1)
v = var2(mtx,mn);
end

if (isreal(mtx))
res = mean(mean((mtx-mn).^3)) / (v^(3/2));
else
res = mean(mean(real(mtx-mn).^3)) / (real(v)^(3/2)) + ...
i * mean(mean(imag(mtx-mn).^3)) / (imag(v)^(3/2));
end

```









Jun 20, 97 20:04

spyrBand.m

Page 1/1

```

% [LEV,IND] = spyrBand(PYR,INDICES,LEVEL,BAND)
%
% Access a band from a steerable pyramid.
%
% LEVEL indicates the scale (finest = 1, coarsest = spyrHt(INDICES)).
%
% BAND (optional, default=1) indicates which subband
% (1 = vertical, rest proceeding anti-clockwise).
%
% Eroo Simoncelli, 6/96.
function res = spyrBand(pyr,pind,level,band)
if (exist('level') ~= 1)
    level = 1;
end
if (exist('band') ~= 1)
    band = 1;
end
nbands = spyrNumBands(pind);
if ((band > nbands) | (band < 1))
    error(sprintf('Bad band number (%d) should be in range [1,%d].', band, nbands)
);
end
maxLev = spyrHt(pind);
if ((level > maxLev) | (level < 1))
    error(sprintf('Bad level number (%d), should be in range [1,%d].', level, maxL
ev));
end
firstband = 1 + band + nbands*(level-1);
res = pyrBand(pyr, pind, firstband);

```

Apr 26, 97 12:50

spyrHigh.m

Page 1/1

```

% RES = spyrHigh(PYR, INDICES)
%
% Access the highpass residual band from a steerable pyramid.
%
% Eroo Simoncelli, 6/96.
function res = spyrHigh(pyr,pind)
res = pyrBand(pyr, pind, 1);

```



May 05, 97 10:55

spyrHt.m

Page 1/1

```

% [HEIGHT] = spyrHt(INDICES)
%
% Compute height of steerable pyramid with given index matrix.
% Ero Simoncelli, 6/96.
function [ht] = spyrHt(pind)
nbands = spyrNumBands(pind);
% Don't count lowpass, or highpass residual bands
if (size(pind,1) > 2)
    ht = (size(pind,1)-2)/nbands;
else
    ht = 0;
end

```

Sep 27, 98 18:14

spyrLev.m

Page 1/1

```

% [LEV,IND] = spyrLev(PYR,INDICES,LEVEL)
%
% Access a level from a steerable pyramid.
% Return as an SxB matrix, B = number of bands, S = total size of a band.
% Also returns an Bx2 matrix containing dimensions of the subbands.
% Ero Simoncelli, 6/96.
function [lev,ind] = spyrLev(pyr,pind,level)
nbands = spyrNumBands(pind);
if ((level > spyrHt(pind)) | (level < 1))
    error(sprintf('Level number must be in the range [1, %d].', spyrHt(pind)));
end
firstband = 2 + nbands*(level-1);
firstind = 1;
for l=1:firstband-1
    firstind = firstind + prod(pind(l,:));
end
ind = pind(firstband:firstband+nbands-1,:);
lev = pyr(firstind:firstind+sum(prod(ind'))-1);

```

May 05, 97 10:55      **spyrNumBands.m**      Page 1/1

```

% [NBANDS] = spyrNumBands(INDICES)
%
% Compute number of orientation bands in a steerable pyramid with
% given index matrix. If the pyramid contains only the highpass and
% lowpass bands (i.e., zero levels), returns 0.
%
% Eroo Simoncelli, 2/97.
function [nbands] = spyrNumBands(pind)

if (size(pind,1) == 2)
    nbands = 0;
else
    % Count number of orientation bands:
    b = 3;
    while ((b <= size(pind,1)) & all( pind(b,:) == pind(2,:)))
        b = b+1;
    end
    nbands = b-2;
end

```

Apr 26, 97 12:50      **steer2HarmMtx.m**      Page 1/1

```

% MTX = steer2HarmMtx(HARMONICS, ANGLES, REL_PHASES)
%
% Compute a steering matrix (maps a directional basis set onto the
% angular Fourier harmonics). HARMONICS is a vector specifying the
% angular harmonics contained in the steerable basis/filters. ANGLES
% (optional) is a vector specifying the angular position of each filter.
% REL_PHASES (optional, default = 'even') specifies whether the harmonics
% are cosine or sine phase aligned about those positions.
% The result matrix is suitable for passing to the function STEER.
%
% Eroo Simoncelli, 7/96.
function mtx = steer2HarmMtx(harmonics, angles, evenorodd)

%=====
% Optional Parameters:
%=====

if (exist('evenorodd') ~= 1)
    evenorodd = 'even';
end

% Make HARMONICS a row vector
harmonics = harmonics(:)';

numh = 2*size(harmonics,2) - any(harmonics == 0);

if (exist('angles') ~= 1)
    angles = pi * [0:numh-1]/numh;
else
    angles = angles(:);
end

%=====

if isstr(evenorodd)
    if strcmp(evenorodd,'even')
        evenorodd = 0;
    elseif strcmp(evenorodd,'odd')
        evenorodd = 1;
    else
        error('EVEN_OR_ODD should be the string EVEN or ODD');
    end
end

% Compute inverse matrix, which maps Fourier components onto
% steerable basis.
imtx = zeros(size(angles,1),numh);
col = 1;
for h=harmonics
    args = h*angles;
    if (h == 0)
        imtx(:,col) = ones(size(angles));
        col = col+1;
    elseif evenorodd
        imtx(:,col) = sin(args);
        imtx(:,col+1) = -cos(args);
        col = col+2;
    else
        imtx(:,col) = cos(args);
        imtx(:,col+1) = sin(args);
        col = col+2;
    end
end

r = rank(imtx);
if (( r ~= numh ) & ( r ~= size(angles,1) ))
    fprintf(2,'WARNING: matrix is not full rank');
end

mtx = pinv(imtx);

```

Dec 16, 02 16:21

steer.m

Page 1/1

```

% RES = STEER(BASIS, ANGLE, HARMONICS, STEERMTX)
%
% Steer BASIS to the specified ANGLE.
%
% BASIS should be a matrix whose columns are vectorized rotated copies of a
% steerable function, or the responses of a set of steerable filters.
%
% ANGLE can be a scalar, or a column vector the size of the basis.
%
% HARMONICS (optional, default is N even or odd low frequencies, as for
% derivative filters) should be a list of harmonic numbers indicating
% the angular harmonic content of the basis.
%
% STEERMTX (optional, default assumes cosine phase harmonic components,
% and filter positions at 2pi*n/N) should be a matrix which maps
% the filters onto Fourier series components (ordered [cos0 cos1 sin1
% cos2 sin2 ... sinN]). See steer2HarmMtx.m
%
% Eero Simoncelli, 7/96.

function res = steer(basis,angle,harmonics,steermtx)

num = size(basis,2);

if ( any(size(angle) ~= [size(basis,1) 1]) & any(size(angle) ~= [1 1]) )
    error('ANGLE must be a scalar, or a column vector the size of the basis elements');
end

%% If HARMONICS are not passed, assume derivatives.
if (exist('harmonics') ~= 1)
    if (mod(num,2) == 0)
        harmonics = [0:(num/2)-1]*2 + 1;
    else
        harmonics = [0:(num-1)/2]*2;
    end
else
    harmonics = harmonics(:);
    if ((2*size(harmonics,1)-any(harmonics == 0)) ~= num)
        error('harmonics list is incompatible with basis size');
    end
end

%% If STEERMTX not passed, assume evenly distributed cosine-phase filters:
if (exist('steermtx') ~= 1)
    steermtx = steer2HarmMtx(harmonics, pi*[0:num-1]/num, 'even');
end

steervect = zeros(size(angle,1),num);
arg = angle * harmonics(find(harmonics~=0))';
if (all(harmonics))
    steervect(:, 1:2:num) = cos(arg);
    steervect(:, 2:2:num) = sin(arg);
else
    steervect(:, 1) = ones(size(arg,1),1);
    steervect(:, 2:2:num) = cos(arg);
    steervect(:, 3:2:num) = sin(arg);
end

steervect = steervect * steermtx;

if (size(steervect,1) > 1)
    tmp = basis' .* steervect';
    res = sum(tmp)';
else
    res = basis * steervect';
end

```

Apr 26, 97 12:50

subMtx.m

Page 1/1

```

% MTX = subMtx(VEC, DIMENSIONS, START_INDEX)
%
% Reshape a portion of VEC starting from START_INDEX (optional,
% default=1) to the given dimensions.
%
% Eero Simoncelli, 6/96.

function mtx = subMtx(vec, sz, offset)

if (exist('offset') ~= 1)
    offset = 1;
end

vec = vec(:);
sz = sz(:);

if (size(sz,1) ~= 2)
    error('DIMENSIONS must be a 2-vector.');
```

```

end

mtx = reshape( vec(offset:offset+prod(sz)-1), sz(1), sz(2) );

```

Apr 28, 97 20:39

upBlur.m

Page 1/1

```

% RES = upBlur(IM, LEVELS, FILT)
%
% Upsample and blur an image. The blurring is done with filter
% kernel specified by FILT (default = 'binom5'), which can be a string
% (to be passed to namedFilter), a vector (applied separably as a 1D
% convolution kernel in X and Y), or a matrix (applied as a 2D
% convolution kernel). The downsampling is always by 2 in each
% direction.
%
% The procedure is applied recursively LEVELS times (default=1).
%
% Eero Simoncelli, 4/97.

function res = upBlur(im, nlevs, filt)

%-----
%% OPTIONAL ARGS:
if (exist('nlevs') ~= 1)
    nlevs = 1;
end
if (exist('filt') ~= 1)
    filt = 'binom5';
end
%-----

if isstr(filt)
    filt = namedFilter(filt);
end

if nlevs > 1
    im = upBlur(im, nlevs-1, filt);
end

if (nlevs >= 1)
    if (any(size(im)==1))
        if (size(im,1)==1)
            filt = filt';
        end
        res = upConv(im, filt, 'reflect1', (size(im)-1)+1);
    elseif (any(size(filt)==1))
        filt = filt(:);
        res = upConv(im, filt, 'reflect1', [2 1]);
        res = upConv(res, filt, 'reflect1', [1 2]);
    else
        res = upConv(im, filt, 'reflect1', [2 2]);
    end
else
    res = im;
end
end

```

Mar 28, 01 10:31

upConv.m

Page 1/1

```

% RES = upConv(IM, FILT, EDGES, STEP, START, STOP, RES)
%
% Upsample matrix IM, followed by convolution with matrix FILT. These
% arguments should be 1D or 2D matrices, and IM must be larger (in
% both dimensions) than FILT. The origin of filt
% is assumed to be floor(size(filt)/2)+1.
%
% EDGES is a string determining boundary handling:
% 'circular' - Circular convolution
% 'reflect1' - Reflect about the edge pixels
% 'reflect2' - Reflect, doubling the edge pixels
% 'repeat' - Repeat the edge pixels
% 'zero' - Assume values of zero outside image boundary
% 'extend' - Reflect and invert
% 'dont-compute' - Zero output when filter overhangs OUTPUT boundaries
%
% Upsampling factors are determined by STEP (optional, default=[1 1]),
% a 2-vector [y,x].
%
% The window over which the convolution occurs is specified by START
% (optional, default=[1,1], and STOP (optional, default =
% step .* (size(IM) + floor((start-1)./step))).
%
% RES is an optional result matrix. The convolution result will be
% destructively added into this matrix. If this argument is passed, the
% result matrix will not be returned. DO NOT USE THIS ARGUMENT IF
% YOU DO NOT UNDERSTAND WHAT THIS MEANS!!
%
% NOTE: this operation corresponds to multiplication of a signal
% vector by a matrix whose columns contain copies of the time-reversed
% (or space-reversed) FILT shifted by multiples of STEP. See corrDn.m
% for the operation corresponding to the transpose of this matrix.
%
% Eero Simoncelli, 6/96. revised 2/97.

function result = upConv(im, filt, edges, step, start, stop, res)

% THIS CODE IS NOT ACTUALLY USED! (MEX FILE IS CALLED INSTEAD)

fprintf(1, 'WARNING: You should compile the MEX version of "upConv.c",\n' f
ound in the MEX subdirectory of matlabPyTools, and put it in your matlab path.
It is MUCH faster, and provides more boundary-handling options.\n');

%-----
%% OPTIONAL ARGS:
if (exist('edges') == 1)
    if (strcmp(edges, 'reflect1') ~= 1)
        warning('Using REFLECT1 edge-handling (use MEX code for other options).');
    end
end

if (exist('step') ~= 1)
    step = [1,1];
end

if (exist('start') ~= 1)
    start = [1,1];
end

% A multiple of step
if (exist('stop') ~= 1)
    stop = step .* (floor((start-ones(size(start)))./step)+size(im))
end

if (ceil((stop(1)+1-start(1)) / step(1)) ~= size(im,1) )
    error('Bad Y result dimension');
end
if (ceil((stop(2)+1-start(2)) / step(2)) ~= size(im,2) )
    error('Bad X result dimension');
end

if (exist('res') ~= 1)
    res = zeros(stop-start+1);
end

%-----

tmp = zeros(size(res));
tmp(start(1):step(1):stop(1), start(2):step(2):stop(2)) = im;

result = rconv2(tmp, filt) + res;

```

Aug 28, 02 21:38

var2.m

Page 1/1

```
% V = VAR2(MTX,MEAN)
%
% Sample variance of a matrix.
% Passing MEAN (optional) makes the calculation faster.
function res = var2(mtx, mn)
if (exist('mn') ~= 1)
    mn = mean2(mtx);
end
if (isreal(mtx))
    res = sum(sum(abs(mtx-mn).^2)) / max((prod(size(mtx)) - 1),1);
else
    res = sum(sum(real(mtx-mn).^2)) + i*sum(sum(imag(mtx-mn).^2));
    res = res / max((prod(size(mtx)) - 1),1);
end
```

Dec 16, 02 16:16

vectify.m

Page 1/1

```
% [VEC] = columnize(MTX)
%
% Pack elements of MTX into a column vector. Just provides a
% function-call notation for the operation MTX(:)
function vec = columnize(mtx)
vec = mtx(:);
```

Apr 26, 97 12:50

wpyrBand.m

Page 1/1

```

% RES = wpyrBand(PYR, INDICES, LEVEL, BAND)
%
% Access a subband from a separable QMF/wavelet pyramid.
%
% LEVEL (optional, default=1) indicates the scale (finest = 1,
% coarsest = wpyrHt(INDICES)).
%
% BAND (optional, default=1) indicates which subband (1=horizontal,
% 2=vertical, 3=diagonal).
%
% Eero Simoncelli, 6/96.

function im = wpyrBand(pyr,pind,level,band)

if (exist('level') ~= 1)
    level = 1;
end

if (exist('band') ~= 1)
    band = 1;
end

if ((pind(1,1) == 1) | (pind(1,2) == 1))
    nbands = 1;
else
    nbands = 3;
end

if ((band > nbands) | (band < 1))
    error(sprintf('Bad band number (%d) should be in range [1,%d].', band, nbands)
);
end

maxLev = wpyrHt(pind);
if ((level > maxLev) | (level < 1))
    error(sprintf('Bad level number (%d), should be in range [1,%d].', level, maxL
ev));
end

band = band + nbands*(level-1);
im = wpyrBand(pyr,pind,band);

```

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wpyrHt.m

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```

% [HEIGHT] = wpyrHt(INDICES)
%
% Compute height of separable QMF/wavelet pyramid with given index matrix.
%
% Eero Simoncelli, 6/96.

function [ht] = wpyrHt(pind)

if ((pind(1,1) == 1) | (pind(1,2) == 1))
    nbands = 1;
else
    nbands = 3;
end

ht = (size(pind,1)-1)/nbands;

```

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wpyrLev.m

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```

% [LEV,IND] = wpyrLev(PYR,INDICES,LEVEL)
%
% Access a level from a separable QMF/wavelet pyramid.
% Return as an SxB matrix, B = number of bands, S = total size of a band.
% Also returns an Bx2 matrix containing dimensions of the subbands.
%
% Eroo Simoncelli, 6/96.
function [lev,ind] = wpyrLev(pyr,pind,level)
if ((pind(1,1) == 1) | (pind(1,2) == 1))
    nbands = 1;
else
    nbands = 3;
end
if ((level > wpyrHt(pind)) | (level < 1))
    error(sprintf('Level number must be in the range [1, %d].', wpyrHt(pind)));
end
firstband = 1 + nbands*(level-1)
firstind = 1;
for l=1:firstband-1
    firstind = firstind + prod(pind(l,:));
end
ind = pind(firstband:firstband+nbands-1,:);
lev = pyr(firstind:firstind+sum(prod(ind'))-1);

```

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zconv2.m

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```

% RES = ZCONV2(MTX1, MTX2, CTR)
%
% Convolution of two matrices, with boundaries handled as if the larger mtx
% lies in a sea of zeros. Result will be of size of LARGER vector.
%
% The origin of the smaller matrix is assumed to be its center.
% For even dimensions, the origin is determined by the CTR (optional)
% argument:
%   CTR   origin
%   0     DIM/2     (default)
%   1     (DIM/2)+1 (behaves like conv2(mtx1,mtx2,'same'))
%
% Eroo Simoncelli, 2/97.
function c = zconv2(a,b,ctr)
if (exist('ctr') ~= 1)
    ctr = 0;
end
if ((size(a,1) >= size(b,1) ) & ( size(a,2) >= size(b,2) ))
    large = a; small = b;
elseif (( size(a,1) <= size(b,1) ) & ( size(a,2) <= size(b,2) ))
    large = b; small = a;
else
    error('one arg must be larger than the other in both dimensions!');
end
ly = size(large,1);
lx = size(large,2);
sy = size(small,1);
sx = size(small,2);
%% These values are the index of the small mtx that falls on the
%% border pixel of the large matrix when computing the first
%% convolution response sample:
sy2 = floor((sy+ctr+1)/2);
sx2 = floor((sx+ctr+1)/2);
clarge = conv2(large,small);
c = clarge(sy2:ly+sy2-1, sx2:lx+sx2-1);

```